

**TOPOLOGIES INDUCED BY  
(3,1, $\rho$ )-METRICS  
AND  
(3,2, $\rho$ )-METRICS**

- The geometric problems in metric spaces, and their axiomatic classification and generalization have been considered in many papers such as:
- [Ne1] V. Nemytzki: On the “third axiom of metric spaces”, Trans. Amer. Math. Soc. 29, 1927, 507-513
- [Me] K. Menger; Untersuchungen über allgemeine Metrik, Math. Ann. 100, 1928, 75-163 .
- [Ne2] V. Nemytzki: Über die Axiome des metrischen Raumes, Math. Ann. 104, No 5, 1931, 666-671
- [AN] P.S. Aleksandrov, V.V. Nemyckii: Uslovija metrizuемости topologičeskikh prostranstv i aksioma simetrii, Mat. sb. 3 : 3, 1938, 663-672

- [M] Z. Mamuzić; Uvod u opstu topologiju, Matematička biblioteka-17, Beograd, 1960;
- [G1] S. Gähler; 2-metrische Räume und ihre topologische Struktur, Math. Nachr. 26, 1963, 115-148
- [A] A.V. Arhangel'skii: O povedenii metrizuemosti pri faktornyx tobrazenijah, DAN 164, No 2, 1965, 247-250
- [N1] S. Nedev: Ob obobščeno metrizuemyih prostranstvah, Dokl. Bolg. Akad. Nauk, 20, No 6, 1967, 513-516
- [NC] S. Nedev, M. Coban: O metrizuemosti topologičeskih grupp, Vestn. Mosk. Un-ta, ser. Matem., meh, No 6, 1968, 18-20

- [G2] S. Gähler, Untersuchungen über verallgemeinerte  $m$ -metrische Räume. I and II, Math. Nach. 40, 1969, 165-189 and 229-264.
- [N2] S. Nedev;  $O$ -metrizuemie prostranstva, Trud. Mosk. Mat. Ob. Tom 24, 1971, 201-236
- [Dh] Dhage, B.C: Generalized metric spaces and topological structure I, An. stiint. Univ. Al.I. Cuza Iasi. Mat(N.S) 46, 2000, 3-24
- [Mu1] Z. Mustafa, B. Sims: Some Remarks Concerning  $D$ -Metric Spaces, Proceedings of the International Conference on Fixed Point Theory and Applications, Valencia (Span), July 2003, 189-198
- [Mu2] Z. Mustafa, B. Sims: A new approach to generalized metric spaces, Jurnal of Nonlinear and Convex Analysis, Vol. 7, Number 2, 2006, 289-297

- I introduced the notion of  $(n,m,\rho)$ -metrics in: Mat. Bilten, 16, Skopje, 1992, 73-76. Here I will discuss only the  $(3,1,\rho)$ -metrics and  $(3,2,\rho)$ -metrics, i.e. the cases  $n=3$ , and  $m=1$  or  $m=2$ .
- Let  $M$  be a nonempty set and let  $\rho \subseteq M^3$ . For a map  $d: M^3 \rightarrow \mathbb{R}$  we state the following conditions:

1)  $d(x,y,z) \geq 0$ ,

2)  $d(x,y,z) = 0$  if and only if  $(x,y,z) \in \rho$ ;

3)  $d(x,y,z) = d(x,z,y) = d(y,x,z)$ ,

4)  $d(x,y,z) \leq d(x,y,u) + d(x,u,z) + d(u,y,z)$ ,

5)  $d(x,y,z) \leq d(x,u,v) + d(y,u,v) + d(z,u,v)$ ,

6)  $d(x,x,y) = d(x,y,y)$ ,

for  $(x,y,z) \in M^3$  and  $(u,v) \in M^2$ .

A map  $d$  satisfying 1), 2), 3) and 4) is called a **(3,1, $\rho$ )-metric**;

1)  $d(x,y,z) \geq 0$ ,

2)  $d(x,y,z) = 0$  if and only if  $(x,y,z) \in \rho$ ;

3)  $d(x,y,z) = d(x,z,y) = d(y,x,z)$ ,

4)  $d(x,y,z) \leq d(x,y,u) + d(x,u,z) + d(u,y,z)$ ,

A map  $d$  satisfying 1), 2), 3) and 5) is called a **(3,2, $\rho$ )-metric**; and

1)  $d(x,y,z) \geq 0$ ,

2)  $d(x,y,z) = 0$  if and only if  $(x,y,z) \in \rho$ ;

3)  $d(x,y,z) = d(x,z,y) = d(y,x,z)$ ,

5)  $d(x,y,z) \leq d(x,u,v) + d(y,u,v) + d(z,u,v)$ ,

A  $(3,1,\rho)$ -metric satisfying 6) is called a  **$(3,1,\rho)$ -symmetric**.

1)  $d(x,y,z) \geq 0$ ,

2)  $d(x,y,z) = 0$  if and only if  $(x,y,z) \in \rho$ ;

3)  $d(x,y,z) = d(x,z,y) = d(y,x,z)$ ,

4)  $d(x,y,z) \leq d(x,y,u) + d(x,u,z) + d(u,y,z)$ ,

6)  $d(x,x,y) = d(x,y,y)$ ,

A  $(3,2,\rho)$ -metric satisfying 6) is called a  **$(3,2,\rho)$ -symmetric**.

1)  $d(x,y,z) \geq 0$ ,

2)  $d(x,y,z) = 0$  if and only if  $(x,y,z) \in \rho$ ;

3)  $d(x,y,z) = d(x,z,y) = d(y,x,z)$ ,

5)  $d(x,y,z) \leq d(x,u,v) + d(y,u,v) + d(z,u,v)$ ,

6)  $d(x,x,y) = d(x,y,y)$ ,

**Remark:** In the notion of  $(n,m,\rho)$ -metrics, the case  $n=2$  allows only one possibility for  $m$ ,  $m=1$ . Then, for a nonempty set  $M$  and  $\rho \subseteq M^2$ , a map  $d:M^2 \rightarrow \mathbb{R}$  is a  $(2,1,\rho)$ -metric if:

- 1)  $d(x,y) \geq 0$ ,
- 2)  $d(x,y) = 0$  if and only if  $(x,y) \in \rho$ ,
- 3)  $d(x,y) = d(y,x)$ , and
- 4)  $d(x,y) \leq d(x,u) + d(u,y)$ ,

for  $(x,y) \in M^2$  and  $u \in M$ .

It follows that  $\rho$  has to be an equivalence relation on  $M$ . If  $\rho = \{(x,x) \mid x \in M\}$ , then the notion of a  $(2,1,\rho)$ -metrics is the notion of a metrics on  $M$ .



If  $d$  is a  $(3,j,\rho)$ -metric, then  $\rho$  has to be a  **$(3,j)$ -equivalence**, for  $j=1$  or  $2$ , i.e.:

1)  $(x,x,x) \in \rho$  ;

2) if  $(x,y,z) \in \rho$ , then  $(x,z,y), (y,x,z) \in \rho$  ;

3.1) if  $(x,y,u), (x,u,z), (u,y,z) \in \rho$ , then  $(x,y,z) \in \rho$  ;

3.2) if  $(x,u,v), (y,u,v), (z,u,v) \in \rho$ , then  $(x,y,z) \in \rho$ .

The set  $\Delta = \{ (x,x,x) \mid x \in M \}$  is a  $(3,j)$ -equivalence for both  $j=1$  and  $j=2$ .

A  $(3,j,\Delta)$ -metric (symmetric)  $d$  is called a  **$(3,j)$ -metric**, ( **$(3,j)$ -symmetric**),  $j=1$  or  $2$ .

Any  $(3,j,\rho)$ -metric  $d$  on  $M$  induces a map  $D:M^2 \rightarrow \mathbb{R}$  defined by  $D(x,y)=d(x,x,y)$ . The map  $D$  satisfies:  $D(x,y) \geq 0$ ; and  $D(x,x)=0$ , and is called a **distance** in  $[M]$  and **pseudo o-metric** in  $[N2]$ .

If  $d$  is a  $(3,j)$ -metric,  $D$  is a **o-metric** as in  $[N2]$ .

If  $d$  is a  $(3,j)$ -symmetric,  $D$  is a **symmetric** as in  $[N2]$ .

If  $d$  is a  $(3,2)$ -symmetric, then  $D$  satisfies:

$D(x,y) \geq 0$ ;  $D(x,y)=0$  iff  $x=y$ ;  $D(x,y)=D(y,x)$ ; and

$D(x,y) \leq 3/2(D(x,z)+D(z,y))$ , and is called **quasimetric, nearmetrics** or **inframetrics**.

Let  $d$  be a  $(3,j,\rho)$ -metric on  $M$ ,  $j=1$  or  $2$ .

For  $\varepsilon>0$ , we define three  $\varepsilon$ -balls, as follows:

$B(x,y,\varepsilon)=\{z \mid d(x,y,z)<\varepsilon\}$ ;  $K(x,\varepsilon)=\{y \mid d(x,y,y)<\varepsilon\}$ ;

$B(x,\varepsilon)=\{y \mid \text{there is a } z, \text{ such that } d(x,y,z)<\varepsilon\}$ .

Next we define several topologies on  $M$ :

a)  $\tau(G,d)$  generated by the  $\varepsilon$ -balls  $B(x,y,\varepsilon)$ ;

b)  $\tau(H,d)$  generated by the  $\varepsilon$ -balls  $B(x,\varepsilon)$ ;

c)  $\tau(D,d)$  generated by the  $\varepsilon$ -balls  $B(x,x,\varepsilon)$ ;

d)  $\tau(N,d)$ :  $U \in \tau(N,d)$  iff  $\forall x \in U, \exists \varepsilon > 0, B(x,x,\varepsilon) \subseteq U$ ;

e)  $\tau(W,d)$ :  $U \in \tau(W,d)$  iff  $\forall x \in U, \exists \varepsilon > 0, B(x,\varepsilon) \subseteq U$ ;

f)  $\tau(S,d)$  generated by the  $\varepsilon$ -balls  $K(x,\varepsilon)$ ;

e)  $\tau(K,d)$ :  $U \in \tau(K,d)$  iff  $\forall x \in U, \exists \varepsilon > 0, K(x,\varepsilon) \subseteq U$ ;

For any  $(3,j,\rho)$ -metric  $d$  on  $M$ ,  $j=1$  or  $2$ , these topologies satisfy the following inclusions:

$$\tau(W,d) \subseteq \tau(N,d) \subseteq \tau(D,d) \subseteq \tau(G,d) ,$$

$$\tau(W,d) \subseteq \tau(H,d) \subseteq \tau(G,d), \text{ and}$$

$$\tau(W,d) \subseteq \tau(K,d) \subseteq \tau(S,d).$$

For a  $(3,2,\rho)$ -metric  $d$  on  $M$ , we have the following additional inclusions:

$$\tau(W,d) \subseteq \tau(N,d) = \tau(K,d) \subseteq \tau(S,d) \subseteq \tau(D,d) \subseteq \tau(G,d).$$

In general, these inclusions are strict.

For each  $X, Y \in \{W, N, D, G, H\}$  we denote by:

a) **Co(X-Y)**

b) **C(X-Y)**

c) **Cos(X-Y)**

d) **Cs(X-Y)**

the class of all topological spaces  $(M, \tau)$ , such that there exist a:

a)  $(3, 1, \rho)$ -metric

b)  $(3, 1)$ -metric

c)  $(3, 1, \rho)$ -symmetric

d)  $(3, 1)$ -symmetric

d, such that  $\tau = \tau(X, d) = \tau(Y, d)$ .

For  $X=Y$ , we write only  $\text{Co}(X)$ ,  $\text{C}(X)$ ,  $\text{Cos}(X)$  and  $\text{Cs}(X)$ .

The class  $C_s(N)$  is the class of symmetrizable spaces, the class  $C_o(N)$  is the class of pseudo o-metrizable spaces, and the class  $C(N)$  is the class of o-metrizable spaces, as in [N2].

The 2-metrizable spaces investigated in [Me] and [G1] are from the class  $C_o(G)$ , with some additional requirements on the set  $\rho$ , i.e. with the requirement that  $d(x,x,y)=0$ .

In [Mu], it is shown that under some additional conditions on a  $(3,1)$ -metric  $d$ , the topological space  $(M, \tau(N,d))$  is a metrizable space.

The class of metrizable spaces is a subclass of each of the above mentioned classes  $C_s(X-Y)$ .

The class  $C_o(N-D)$  is the class of all the topological spaces satisfying the I axiom of countability.

The classes  $C_{os}(N-D)$  and  $C_{os}(W-G)$  coincide. Similarly,  $C_s(N-D)=C_s(W-G)$ .

**Question:**

**What are the classes:  $C_s(W-G)$ ,  $C(W-G)$ ???**

For a  $(3,1,\rho)$ -metric  $d$  on a set  $M$ , the map  $F_{ab} : M \rightarrow \mathbb{R}$ , defined by  $F_{ab}(x)=d(a,b,x)$ , in general, is not continuous for  $a,b \in M$  and any induced topology on  $M$  by  $d$ .

But, for any  $a \in M$  the multivalued map  $F_a : M \rightarrow \mathbb{R}$ , defined by  $F_a(x)=\{d(a,x,y) \mid y \in M\}$  is l.s.c for the induced topologies  $\tau(G,d)$  and  $\tau(H,d)$ .

**Questions:**

**What conditions on  $d$  would imply the existence of a continuous selection for  $F_a$  ??**

**What is the subclass of  $C(W-G)$ ,  $(C_s(W-G))$  satisfying the property that each  $F_a$  has a continuous selection ???**



**Example:** Let  $M=\mathbb{R}$ , and let  $d:M^3\rightarrow\mathbb{R}$  be defined by:

$$d(x,x,x)=0$$

$$d(x,y,y)=1 \text{ for } x<y$$

$$d(x,y,y)=y-x \text{ for } y\leq x$$

$$d(x,y,z)=\max\{z-y, |z-y-1|\} \text{ for } x<y<z.$$

This  $d$  is a  $(3,1)$ -metric,

$$\tau(W,d)=\mathcal{J}, \quad \tau(H,d)=\tau(G,d)=\mathcal{D},$$

$\tau(N,d)=\tau(D,d)=\tau$  is generated by the half open intervals  $[x,y)$ ,  $((\mathbb{R},\tau)$  is called Sorgenfrey line),

$\tau(K,d)=\tau(S,d)$  is generated by the half open intervals  $(x,y]$ .