

Providing Arguments in Discussions on the Basis of the Prediction of Human Argumentative Behavior

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Argumentative discussion is a highly demanding task. In order to help people in such discussions, this article provides an innovative methodology for developing agents that can support people in argumentative discussions by proposing possible arguments. By gathering and analyzing human argumentative behavior from more than 1000 human study participants, we show that the prediction of human argumentative behavior using Machine Learning (ML) is possible and useful in designing argument provision agents. This paper first demonstrates that ML techniques can achieve up to 76% accuracy when predicting people's top three argument choices given a partial discussion. We further show that well-established Argumentation Theory is not a good predictor of people's choice of arguments. Then, we present 9 argument provision agents, which we empirically evaluate using hundreds of human study participants. We show that the Predictive and Relevance-Based Heuristic agent (PRH), which uses ML prediction with a heuristic that estimates the relevance of possible arguments to the current state of the discussion, results in significantly higher levels of satisfaction among study participants compared with the other evaluated agents. These other agents propose arguments based on Argumentation Theory; propose predicted arguments without the heuristics or with only the heuristics; or use Transfer Learning methods. Our findings also show that people use the PRH agents proposed arguments significantly more often than those proposed by the other agents.

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1. INTRODUCTION

Argumentative dialogs are part of everyday life. Nevertheless, participating in argumentative dialogs can be a highly demanding task for humans, both mentally and emotionally, as shown in discursive psychology research [Edwards 1997; Krauss 2001]. An

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intelligent, automated agent can help relieve some of these demands by providing contextual arguments for its human user to use while she engages in an argumentative dialog. This can be achieved using the agent's computational advantage and knowledge over humans' argumentative behavior.

When suggesting an argument to a human user, an agent can consider two possible approaches. First, the agent can suggest an argument that the person has (probably) considered and is prone to use anyway. Second, it can suggest an innovative argument that the person has (probably) not considered.

In order to estimate which arguments a person is likely to use in a given discussion, an agent can use several prediction methods:

- (1) Argumentation Theory (see [Walton 2009] for an excellent summary) can be used to logically analyze argumentative discussions. This analysis can be used as a prediction of which arguments a deliberant might use.
- (2) Heuristics can account for the temporal nature of the argumentative dialog and provide a prediction of which arguments are likely to be used next given the current state of the dialog. For example, a simple heuristic might predict that a user's next argument will directly relate to the last argument presented in the dialog.
- (3) Machine Learning (ML) techniques, utilizing previous argumentative choices of *other* users on the same topic, can provide a prediction of which argument is expected to be presented next in a discussion. That is, ML can estimate the probability of each argument to be used next in a given dialog based on previous records of human argumentative choices in similar dialogs on the same topic.
- (4) Transfer Learning (TL) methods (see [Pan and Yang 2010] for a survey) can use previous argumentative discussions by *the same user* and transfer the observed argumentative selections to a new domain, specified as the *target domain*. Given a partial discussion in the target domain, a prediction of the next presented argument in the discussion is generated according to the user's argumentative selections in *other domains*.

In this work, we first tackle the problem of predicting human argumentative behavior. We present a comprehensive empirical evaluation of the above four prediction methods. Thus far, the suggested prediction methods were not examined with respect to their predictive abilities in predicting human argumentative behavior. To evaluate the four suggested methods we conducted a series of four experiments varying in their argumentative complexity: from multiple choice argumentative questionnaires based on argumentative scenarios taken from the literature, to on-line chats in natural language where two deliberants engage in an online discussion over a controversial topic. Next, we present 9 novel argument provision agents, based on the aforementioned prediction methods. These agents are extensively evaluated in online discussions with hundreds of human study participants.

With this extensive human study, with over 1000 human study participants¹ spread across 4 experiments, we make the following contributions;

- (1) We establish the lack of predictive abilities of the existing Argumentation Theory in all of the examined experimental settings.
- (2) We show that ML can be an extremely useful tool in predicting human argumentative behavior in the real world.
- (3) We introduce the heuristics of *Relevance*, which integrates the concept of Bounded Rationality [Gigerenzer and Selten 2002] into Argumentation Theory. We further

¹All experiments were authorized by the corresponding IRB.

demonstrate the potential that the Relevance heuristics hold in predicting human argumentative behavior in human discussions.

- (4) We show that the combination of ML prediction and the Relevance heuristics significantly outperforms 8 other argument provision agents. These agents propose arguments based on Argumentation Theory, heuristics, predicted arguments without the heuristics or predicted arguments using a Transfer Learning method. The agent combining ML prediction with the Relevance heuristics, entitled PRH, achieved significantly superior results on both of the axes that we examined, i.e. peoples subjective satisfaction from the agent and people’s use of its suggested arguments.

The remainder of the paper is organized as follows. In Section 2 we survey related work and provide an overview of the models used in the scope of this study. In Section 3 we present a comprehensive empirical evaluation of the four suggested prediction methods of human argumentative behavior. In Section 4 we describe the design and evaluation of 9 novel argument provision agents. Finally, in Section 5 we provide a summary and list recommendations for future work in this area.

2. RELATED WORK AND BACKGROUND

Since the time of Aristotle there have been many frameworks for argumentative behavior which have been proposed by philosophers and mathematicians alike. To date, argumentation researchers have extensively studied the concept of a “good” argument and have proposed many models explaining how to identify these arguments [Walton 2009]. Most of the state-of-the-art models, which are known as Argumentation Theory, rely on some fundamental notions from [Dung 1995] and expand them in some way. These include the Bipolar Argumentation Framework (BAF) [Cayrol and Lagasquie-Schiex 2005], the Value Argumentation Framework (VAF) [Bench-Capon 2003] and the Weighted Argumentation Framework (WAF) [Dunne et al. 2011], to name a few (see [Brewka et al. 2014] for a recent review). This haystack of theories is based on similar principles and ideas. It is common in Argumentation Theory to define some argumentation framework – a formalized structure in which statements (arguments) can attack or support each other. Using different reasoning rules (semantics) it is possible to build sets of justified arguments (arguments that should be considered correct to some extent), and thereby solve the inherent conflicts. The basic notions suggested in [Dung 1995] are available in Appendix A.

Throughout this work, we use the BAF modeling proposed in [Cayrol and Lagasquie-Schiex 2005], to which we will refer as the “argumentation framework”.

Definition 2.1. A Bipolar Argumentation Framework (BAF) $\langle A, R, S \rangle$ consists of a finite set A called arguments and two binary relations on A called attack (R) and support (S).

The BAF modeling assumes 2 types of possible interactions between arguments; attack and support. That is, if argument $a \in A$ relates to argument $b \in A$, then aRb or aSb holds, respective of the relation type. It is argued that the use of both support and attack relations in argumentation frameworks is essential to represent realistic knowledge (see [Amgoud et al. 2008] for a survey).

The argumentation framework can also be represented as a directed graph with 2 types of edges². A is the set of vertices, and R, S , are the sets of directed edges representing attack and support relations.

²Sometimes called a bipolar interaction graph.

In order to be able to perform reasoning about an argumentation framework, it is necessary to define reasoning rules, called *semantics*. Dung [Dung 1995] has defined several semantics which have been modified to fit the BAF modeling [Amgoud et al. 2008]. In this work, we examine the 3 classical semantics proposed by Dung — Preferred, Grounded and Stable (see Appendix A). Using the above semantics, a reasoner can identify sets of arguments, called *extensions*, which hold the special properties requested by the semantic. An argument which is a member of some extension is considered acceptable or justified (to some extent).

Given a BAF $\langle A, R, S \rangle$, a discussion d is a finite sequence of arguments $\langle a_1, a_2, \dots, a_n \rangle$ where $a_i \in A$. A discussion d can be split into 2 argument sets A_1 and A_2 , where $A_i = \{a_j \mid a_j \in d \wedge a_j \text{ was presented by study participant } i\}$. That is, every conversation can be seen as 2 argument sets A_1 and A_2 , one per participant in the conversation. When examining whether a set of arguments A_i is a part of some extension, one can consider the calculated extensions of the entire BAF. However, one can also consider the extension derived only on the basis of arguments in d , that is, one can calculate the extension of a BAF consisting only of A_1 and A_2 's arguments. We denote this BAF as the *restricted* argumentation framework induced by $A_1 \cup A_2$.

Definition 2.2. Let $W = \langle A, R, S \rangle$ be a BAF, and $A' \subseteq A$ be an argument set. The *restricted BAF* induced by A' is defined as $W \downarrow_{A'} = \langle A', R \cap A' \times A', S \cap A' \times A' \rangle$.

The Preferred, Grounded and Stable semantics coincide on a single unique extension if the argumentation framework is *well founded*.

Definition 2.3. Let W be a BAF. W is *well founded* if there exists no infinite sequence $a_0, a_1, \dots, a_n, \dots$ such that $\forall i. (a_i, a_{i+1}) \in R \cup S$.

The understanding of the connections between human reasoning and Argumentation Theory is a key requirement for deploying Argumentation-based software and agents in practical applications. To date, very little investigation has been conducted regarding how well the proposed models and semantics describe human reasoning. To the best of our knowledge only two other papers directly address this topic; Rahwan et al. [Rahwan et al. 2010] studied the reinstatement argumentative principle in questionnaire-based experiments and Cerutti et al. [Cerutti et al. 2014] examined humans' ability to comprehend formal arguments. The above works did not examine the possibility of Argumentation Theory predicting people's argumentative behavior nor did they try to use their insights to generate advice or recommendation for a human user. Baroni et al. [2015] recently provided a conceptual analysis and discussion on the incompleteness and undecidedness in Argumentation Theory, which are also common in human reasoning. However, they did not evaluate or consider human argumentative behavior.

Computer-supported argumentation systems have received much attention in the last 20 years [Scheuer et al. 2010]. Such systems are prominent in law, education, formal reasoning and collaborative discussions. These systems implement a *normative* approach to argumentation, i.e, how argumentation should work from a logical standard. For example, ArgTrust [Parsons et al. 2013] provides an argumentation-based software which provides users the means to handle argumentative situations in a coherent and valid manner. MIT's delibrium [Klein 2011] provides an interactive web-based system to allow multiple, distant users to engage in a discussion in a logical manner. To the best of our knowledge, no argumentation-based system deploys a *descriptive* approach, i.e, accounts for how argumentation actually works in human reasoning. In this work we examine the implementation of both the normative model (i.e, Argumentation Theory) and descriptive models (i.e, Heuristics, ML and TL), first

to predict human argumentative behavior, then to provide arguments during a discussion.

Others studies have addressed agents' strategical considerations in argumentative environments involving people. In [Dsouza et al. 2013], the authors investigate which information an agent should reveal during a deliberation with people. Others have developed policies for the generation of offers in human-agent negotiations [Rosenfeld et al. 2014], or the generation of arguments in automated sales-clerk interactions with human customers [Hiraoka et al. 2014]. None of these works are in the context of Argumentation Theory, nor have any of these researchers considered providing arguments or recommendations to the human user.

In Section 3.3 we introduce the heuristics of *Relevance*, which relies on the concept of *proximity* between arguments. Booth et al. have provided a formal analysis of proximity between different evaluations of arguments [Booth et al. 2012]. Both notions use distance and proximity measurements to derive insights mainly based on the argumentation framework's structure. However, our concept of proximity is completely independent of the one presented in [Booth et al. 2012] as we do not consider the evaluation of arguments in our distance measurements.

Conversational Agents³ (CAs) have been developed over the year to converse with humans and provide information or assistance to the users' satisfaction [Cassell 2000; Berg 2015]. In the CAs framework, a human user directly interacts with the CA and explicitly conveys her wishes. The CA can also ask the user questions that will help it understand the user's goals or requests. In this work we deal with a different setting in which 2 people converse while the advising agent cannot take an active part in the conversation. Specifically, the agent can only observe the dialog, and its sole mean of communication with its user is by providing arguments for her to use.

At first glance, our proposed approach can be viewed as part of the Case-Based Reasoning (CBR) approach [Watson 1999]. In CBR, a reasoner *retrieves* relevant past cases from memory, *reuses and revises* the solutions from these previous cases to generate a solution in the target problem, and *retains* the generated solution for future use. In our setting, the advising agent can use rules learned by machine learning algorithms to find suitable arguments to propose (similar to the retrieval phase). These arguments can be used by the agent (depending on its policy) to generate an argument list to propose to its user (similar to the reusing and revising phase), and the user's choices can be stored for future use (similar to the retaining phase). However, our proposed approach is quite different from CBR; First, our approach does not require past *advising cases* to derive an advising policy but merely past dialogs on the topic. Note that the CBR approach necessitates the identification of a great deal of tasks that were already solved successfully in the past. In our setting, the task is to provide beneficial advice during an argumentation discussion. Attaining an abundant collection of successful advising cases can be extremely expensive. Furthermore, our approach forms its generalizations of the given dialogs by identifying commonalities between the training examples in an offline fashion before the actual dialog takes place. In the CBR approach the commonalities between the retrieved examples and the target problem are carried out in an online setting which can pose a difficulty in fast changing dialogs.

The two argument provision approaches we examine in this paper hold different rational-psychological explanations for why people would benefit from the suggested arguments. First, people search for *validation* for their existing opinions and beliefs [Linehan 1997]. Thus, receiving consonant (supportive) arguments for their views from an intelligent agent can help validate the person's beliefs. Second, Rational Choice Theory [Coleman and Fararo 1992] suggests that when an individual considers an

³Also known as dialog systems.

action (e.g., argument to use) she needs to weigh all information that can or will affect that argument. An agent can help a user in this task by revealing additional arguments, i.e, arguments of which the user was unaware, or by assisting the user in weighing the different arguments in an analytic manner.

It is common in literature to distinguish between different types of argumentation-structures [Walton et al. 2009]. Throughout this work, we focus on *deliberations*, where the discussion process is aimed at exchanging opinions, beliefs and information and trying to reach some consensus on a controversial topic. In the scope of this study, the agent's goal is to provide arguments which its user will find satisfactory. Future work will expand the suggested methodology to account for more complex argumentation-structures such as persuasion and negotiation where an argument provision agent will be required to assist the user in constructing more convincing and compelling arguments.

The development of automated argumentation-based agents, such as the ones presented in this study, necessitates the assumption that natural language statements can be automatically mapped into arguments. Despite recent advancements in Natural Language Processing (NLP) and Information Retrieval (IR) and their studied connections to argumentation [Modgil et al. 2013; Cabrio et al. 2014; Moens 2014], this assumption is not completely met by existing automated tools. Hence, throughout this work we use a human expert annotator whom we hired as a research assistant. We hope that this work will inspire other researchers in NLP and IR to tackle the problem of automatically mapping natural language statements into arguments as well as other open problems of great importance in argumentation-based systems. These include the automatic extraction of arguments from texts [Fan et al. 2012] and the automatic identification of relations between natural language arguments [Slonim et al. 2014].

3. PREDICTING PEOPLE'S ARGUMENTATIVE BEHAVIOR

In this section we investigate the predictive abilities of the four proposed prediction methods: Argumentation Theory, Relevance Heuristics, Machine Learning (ML) and Transfer Learning (TL). To that aim, we first collect extensive data in several experimental settings, varying in complexity, in which human study participants were asked to use arguments. We provide a full description of three experimental settings, followed by an analysis of the gathered data using three of the proposed prediction methods: Argumentation Theory, Relevance Heuristics and ML. Then, we describe an additional experiment (Experiment 4) followed by an analysis of the gathered data using the TL prediction method.

The suggested prediction methods examined in this section were also used in the design of the 9 argument provision agents developed in the scope of this study (see Section 4).

3.1. Experimental Design

3.1.1. Experiment 1 — Questionnaire-based argumentation. Two groups took part in this experiment. The first group consisted of 64 US residents, all of whom work for Amazon Mechanical Turk (AMT). These study participants, denoted the US-Group, ranged in age from 19 to 69 (mean=38, s.d.=13.7), with 38 females and 28 males. The second group consisted of 78 Israeli Computer Science Bachelor students, denoted the IL-Group, ranged in age from 18 to 37 (mean=25, s.d.=3.7), with 27 females and 51 males. The study participants were presented with 6 fictional scenarios based on scenarios from [Walton 2005; Arvapally and Liu 2012; Cayrol and Lagasquie-Schiex 2005; Amgoud et al. 2008; Parsons et al. 2013]. The scenarios are available in Appendix B. Small changes were made in the original formulation of the scenarios in order to keep

the argumentation frameworks small (6 arguments) and simply phrased, yet the scenarios were kept as close as possible to the original. Each scenario was presented as a short conversation between the 2 deliberants and the study participant had to choose which of the 4 possible arguments she would use next if she was one of the deliberants participating in the conversation. The following example is one of the 6 scenarios we presented to the study participants:

Example 3.1. A couple is discussing whether or not to buy an SUV.
 Spouse number 1 (S_1): “We should buy an SUV; it’s the right choice for us”.
 Spouse number 2 (S_2): “But we can’t afford an SUV, it’s too expensive”.
 The study participant was then asked to put himself in S_1 ’s place and choose the next argument to use in the deliberation⁴.
A. Good car loan programs are available from a bank.
B. The interest rates on car loans will be high.
C. SUVs are very safe, safety is very important to us.
D. There are high taxes on SUVs.

The 6 scenarios were similar in the way in which they were presented: a short conversation of 2 statements and 4 possible arguments from which the study participant was asked to select her preferred argument. However, the argumentative frameworks they induced were different in order to simulate different argumentative complexity levels. Figure 1 presents a graphical representation of the example. This graphical representation was *not* presented to the study participants.

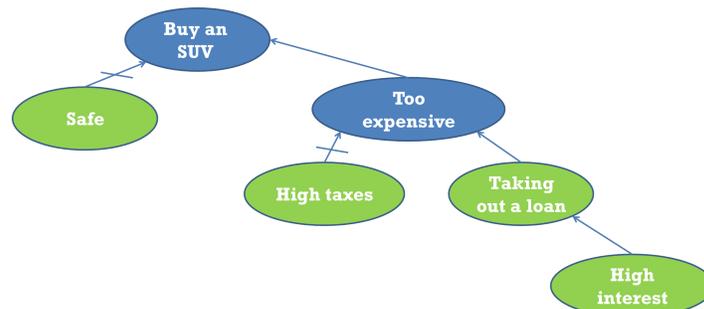


Fig. 1: BAF: nodes are arguments. Arrows indicate attacks and arrows with diagonal lines indicate support.

3.1.2. Experiment 2 — Real phone conversations (secondary data). For this experiment we used real argumentative conversations from the Penn Treebank Corpus (1995) [Marcus et al. 1993]. Hence, Experiment 2 is in fact an analysis of *secondary data*. The Penn Treebank Corpus includes hundreds of transcribed telephone conversations on controversial topics such as “Should Capital Punishment be implemented?” and “Should trial sentencing be decided by a judge or jury?”, on which we chose to focus. We reviewed all 33 deliberations on “Capital Punishment” and 31 deliberations on “Trial by Jury” in order to map the presented utterances into arguments. This process required the

⁴The options were shuffled to avoid biases.

clearing of irrelevant sentences (i.e, greetings, unrelated talk, etc.) and the construction of an argumentation framework comprising all of the arguments presented in the conversations.

The annotation process was performed manually by a human expert; first, the annotator read 5 conversations that were selected at random from the corpus to get an initial idea of which arguments people use. Then, the annotator went over all conversations on a topic, one at a time, and classified each statement presented in the conversation into one of the following categories: 1) Arguments, 2) Opinions and 3) Others. The Arguments class consists of all relevant arguments that were presented on a topic in the corpus. The Opinions class consists of all statements that reflect the speaker's opinion on the discussed topic such as "I'm pro X" or "I oppose the Y idea". All other statements such as greetings or unrelated talk were classified to the Others class. Once all statements were classified, the annotator went over all presented arguments and constructed an argumentation framework by identifying support and attacks between arguments. In cases where the human expert was unsure of his annotation or the relation between arguments, a second human expert was asked to provide a final decision. Then, the presented opinions were mapped into "pro" and "con" sub-classes. Finally, the annotator translated each conversation into a series of arguments (with respect to the constructed framework) and opinions (according to their sub-classification to "pro" and "con"), providing us with 33 sequences on "Capital Punishment" and 31 sequences on "Trial by Jury".

The shortest sequence is of size 4 and the longest is of size 15 (a mean of 7).

Unfortunately, the participants' demographic data is unavailable.

3.1.3. Experiment 3 — Semi-structured online chats. For Experiment 3 we developed a special chat environment. In our chat environment deliberants only communicate by using arguments from the pre-defined argument list. We chose the topic of "*Would you get an influenza vaccination this winter?*" and constructed a pre-defined argument list consisting of Pro (20) and Con (20) arguments. These arguments were extracted from debate sites⁵ and medical columns⁶. In order to bolster the natural flow of the dialog, study participants were also provided with a "bank of discourse statements", comprised of a set of discourse markers and short statements such as "I agree", "I think that", "However" and others. The "bank of discourse statements" allows users to express themselves more naturally. Unlike Experiment 2, the collected chats in Experiment 3 are not considered to be natural chats but rather semi-structured chats.

We recruited 144 Israeli college students to participate in this experiment, ranging in age from 20 to 36 (mean of 27), with 64 females and 80 males. Participants were coupled at random and were asked to deliberate over the question "*Would you get an influenza vaccination this winter?*" for a minimum of 5 minutes. Deliberations ranged in length from 5 arguments to 30 (mean 14). Each deliberation ended when one of the deliberants chose to exit the chat environment.

3.2. Analysis using Argumentation Theory to Predict People's Arguments

People's decision-making processes are known to be affected by a multitude of social and psychological factors and they often do not maximize expected utilities or use equilibrium strategies [Camerer 2003; Rosenfeld et al. 2012]. The question we investigate in this section is whether, in the context of argumentative discussions, people would choose justified arguments according to some semantic choice. That is, would Argu-

⁵such as <http://www.debate.org/>, <http://idebate.org/>

⁶such as <http://healthresearchfunding.org/pros-cons-flu-shots/>

mentation Theory provide predictive tools to predict human argumentative behavior. Appendix A provides an overview of the concepts used in the following analysis.

Recall that each of the tested scenarios in Experiment 1 and each of the tested domains in Experiments 2 and 3 was mapped into an argumentation framework as described in Section 3.1. In order to analyze the data, we first calculated the Grounded, Preferred and Stable extension for each of the resulting argumentation frameworks.

In Experiment 1, each of the 6 tested scenarios (Appendix B) was mapped into a *well founded* (definition 2.3) BAF. As such, the three tested semantics coincide - only one extension is Grounded, Stable and Preferred. On average, in the 6 tested scenarios of Experiment 1, a justified argument was selected only 67.3% of the time (under the tested semantics, i.e. Preferred, Grounded and Stable). Moreover, only 8% of the participants chose justified arguments in all 6 scenarios. Note that in all 6 scenarios more than a single justified argument was available. If we were to predict one of the justified arguments in each of the 6 examined scenarios, the expected accuracy of our prediction model would be 32%. This result is only slightly better than random selection (selecting 1 argument out of 4 – 25%) and worse than using majority prediction (43%), which is predicting the argument that the majority of participants chose in the examined scenario.

For example, in the SUV scenario (see Figure 1), most people (72%) chose the “Taking out a loan” or “High taxes” arguments which directly relate to the last argument presented in the discussion. The “Taking out a loan” argument was the most popular one (37%). However, the “Taking out a loan” argument is supposed to be considered weaker than the other 3 possible arguments as it is not a part of the Grounded, Preferred and Stable extension. The other 3 arguments should be considered justified (as they are unattacked and part of the Grounded, Preferred and Stable extension), whereas “Taking out a loan” is attacked by a justified argument (“High interest”) and is not part of the Grounded, Preferred and Stable extension. Such phenomena were encountered in all other scenarios as well.

In Experiments 2 and 3, the resulting 3 argumentation frameworks on “Capital Punishment”, “Trial by Jury” (Experiment 2) and “Influenza Vaccination” (Experiment 3) were mapped into BAFs. In the resulting BAFs the Grounded, Preferred and Stable semantics do not coincide on a single extension. The argumentation framework for “Capital Punishment” consisted of 30 arguments, the argumentation framework for “Trial by Jury” consisted of 20 arguments and the argumentation framework for “Influenza Vaccination” consisted of 40 arguments.

Experiments 2 and 3 differ from Experiment 1 as they are comprised of discussions between study participants. Each discussion was split into 2 argument sets, A_1 and A_2 , comprising the arguments used by each of the participating parties of the discussion. Each discussion was analyzed twice: First, each of the argument sets comprising the discussion was examined with respect to the argumentation framework consisting of all arguments on the topic. Second, each of the argument sets was examined with respect to the *restricted* argumentation framework induced by the argument sets of the discussion (see definition 2.2).

On average across the 3 domains, when examining the original framework, less than 35% of A_i s used by the study participants were a part of some extension, with Preferred, Grounded and Stable performing very similarly (34%, 35%, 27%). When considering the restricted argumentation framework, 47%, 50% and 39% of the deliberants used A_i s that were part of some extension prescribed by Preferred, Grounded and Stable (respectively) under the restricted framework. See Table I for a summary.

	Preferred		Grounded		Stable	
	orig.	rest.	orig.	rest.	orig.	rest.
“Capital Punishment”	20%	47%	25%	40%	21%	33%
“Trial by Jury”	36%	50%	34%	59%	30%	40%
“Influenza Vaccination”	38%	44%	38%	49%	30%	41%

Table I: Semantics’ accuracy in describing study participants’ arguments with respect to the corresponding original (orig.) argumentation framework and the restricted (rest.) argumentation framework.

More surprising was the fact that even the mildest requirement suggested by Argumentation Theory was not upheld by many study participants. We tested the arguments that the study participants used in the context of *Conflict-Freedom* (CF). In particular, we checked whether the study participants refrained from using contradictory arguments in different stages of the discussion. CF is probably the weakest requirement from a set of arguments. We anticipated that all study participants would adhere to this requirement, yet only 78% of the deliberants used a conflict-free argument set. Namely, 22% of the deliberants used at least 2 conflicting arguments, i.e., one argument that contradicts the other, during their discussions.

3.3. Analysis using Relevance Heuristics

At a given point in a deliberation, not all arguments are necessarily relevant to the context of the deliberation (i.e., the current focus of the deliberation)⁷. For instance, the argument “Safe” in our example (Figure 1) seems to be irrelevant to the current focus of the discussion, since the focus is on economic concerns. First, in order to identify “relevant” arguments, we propose several distance measurements that heavily rely on the current state of the deliberation and the structure of the argumentation framework. These distance measurements will help us investigate how the *proximity* between arguments, as portrayed by the edge-distance in the argumentation framework, truly affects the course of a deliberation.

We defined 15 relevance measurements, each of which captures different aspects of proximity. In the definitions, a denotes a possible argument, a_l is the last argument presented in the discussion, a_c is the “closest” argument to a which was previously presented in the dialog (using edge-distance metric) and Ω denotes a designated argument which represents the discussed issue (in Figure 1 it is whether or not to “Buy an SUV”). The relevance measurements of a possible argument a can be summed up in the following 4 points:

- (1) Minimum un/directed paths’ length from a to a_l .
- (2) Minimum un/directed paths’ length from a to a_c .
- (3) Minimum directed paths’ length from a to Ω .
- (4) Minimum of all/some of the above features.

When omitting redundant calculations in the 4th criteria (for example, the minimum of the shortest directed and undirected paths from a to a_l), 15 distinct measurements remain, denoted d^1, \dots, d^{15} .

In the SUV scenario, S_2 ’s argument is considered as a_l , and Ω is S_1 ’s argument (“Buy an SUV”). When we consider a as “Safe”, its distance to a_c or Ω (in this case, they are

⁷Not to be confused with the concept introduced in [Liao and Huang 2013], which states that it might not be necessary to discover the status of all arguments in order to evaluate a specific argument/set of arguments.

the same) is 1, while its directed distance to a_l is undefined and the undirected distance is 3. If a is “Taking out a loan” then its distance to a_l and a_c is 1, whereas its distance to Ω is 2.

Note that as arguments are presented during a discussion, some of the arguments’ relevance heuristic values may change.

Given the current state of deliberation, each of the proposed distance metrics induces a partial order ranking over all arguments in the argumentation framework. To perform a prediction using d^i , we compute and predict $\text{argmin}_a d^i(a, a_l, a_c, \Omega)$, where ties are broken randomly. That is, after an argument has been put forward we compute $d^i(a, a_l, a_c, \Omega)$ for every argument $a \neq a_l$ given a_l, a_c and Ω (as observed in the partial conversation and the argumentation framework). Then, we rank the arguments accordingly and predict the top ranking argument. The process was repeated for all 15 proposed measurements, d^1, \dots, d^{15} , resulting in 15 predictions for every argument presented in every discussion.

In all 3 experiments, the directed paths’ length from a to a_l (denoted d^1), the directed paths’ length from a to Ω (denoted d^2) and their combination (the minimum between d^1 and d^2 , denoted d^3), yield the highest average prediction accuracy averaging 38%, 15%, 16% in Experiments 1, 2 and 3 respectively. No statistically significant difference was found between d^1, d^2 and d^3 . The other 12 measurements performed significantly worse, averaging 25%, 5%, 5% in Experiments 1, 2 and 3, respectively. See Table II for a summary.

Distance Measurement	Experiment 1	Experiment 2	Experiment 3
Directed paths’ length from a to a_l (d_1)	35%	17%	15%
Directed paths’ length from a to Ω (d_2)	40%	15%	17%
Minimum $\{d^1, d^2\}$ (d_3)	37%	14%	16%
Others (average)	25%	5%	5%

Table II: Relevance prediction accuracy across Experiments 1, 2 and 3.

Specifically, in the SUV scenario, the prediction using d_1 would predict either “Taking out a load” or “High taxes” (randomly, as they both have the minimal distance value of 1). The prediction using d_2 would predict “Safe”, and the prediction using d_3 would predict “Taking out a load”, “High taxes” or “Safe” (randomly).

In Experiments 2 and 3 there are many more arguments to consider in the prediction compared to Experiment 1. Naturally, the prediction accuracy declined. However, we can use the ranking induced by d^i and predict more than 1 argument – that is, we can predict the top k ranked arguments w.r.t their relevance values. When predicting the top 3 ranking arguments, d^1, d^2 and d^3 average 57% prediction accuracy across Experiments 2 and 3. Again, no statistically significant difference was found between them. The other 12 measurements performed significantly worse, averaging 35% across Experiments 2 and 3.

3.4. Analysis using Machine Learning to Predict People’s Arguments

The use of ML in predicting human behavior has shown much promise in developing automated human-interacting agents; a few recent examples are [Rosenfeld 2015;

Rosenfeld et al. 2015; Rosenfeld et al. 2015; Azaria et al. 2015; Peled et al. 2013]. However, the use of ML for the prediction of human argumentative behavior has not been investigated thus far.

A task of predicting human argumentative choices in a discussion can be defined as a multi-class prediction problem. We seek to construct a prediction function $P : \chi \rightarrow A$, where $\vec{x} \in \chi$ is a feature vector (sampled from the feature space χ) representing both the deliberant characteristics and the discussion's state, and $a \in A$ is an argument that is predicted to be presented next in a deliberation given \vec{x} .

For this purpose, we first suggest the characterization of *arguments* in the argumentation framework. For every argument a in the argumentation framework, we suggest a calculation of a measurement vector m_a . m_a describes a in the context in which it is judged (the context in which a reasoner evaluates the argument). That is, in a given state of the discussion, m_a represents the characteristics of a with respect to the current state of the discussion. Hence, m_a might require an update after each presented argument in the discussion by either of the deliberants. We divide m_a into 3 categories; *Justification* measurements, *Relevance Heuristic* values and *Confirmation Factor*.

Given the characterization of *arguments*, we then present the procedure by which we compute \vec{x} - the *feature vector* used in our prediction model P . \vec{x} relies on the arguments presented in the discussion and their characteristics. We divide these features into 2 categories; the *Deliberant features* and the *Deliberation context features*, together comprising \vec{x} . That is, \vec{x} represents both the deliberant and the deliberation using a vector of feature values.

3.4.1. The characterization of arguments.

Justification: There have been a number of proposals for more sophisticated analysis of argumentation frameworks. These proposals mainly consider the relative strength of the arguments or the authority of the party who presented the argument (e.g. [Pazienza et al. 2015]). One commonly used proposal is the gradual valuation [Cayrol and Lagasquie-Schiex 2005] in BAFs. The idea is to evaluate the *relative strength* of argument a using some aggregation function that conciliates between its attacking arguments' strength and its supporting arguments' strength. This recursive calculation allows us to aggregate the number of supporters and attackers, as well as their strength, through the argumentation framework and reach a strength value in a (possibly bounded) interval (e.g. [-1,1]) for each argument. Note that given an argumentation framework $\langle A, R, S \rangle$ and an argument $a \in A$, the identification of a 's attackers ($R(a)$) and a 's supporters ($S(a)$) is straightforward. The technical definition of the gradual valuation functions, as well as its most popular instantiation which is used in this paper, is provided in Appendix D. We denoted this gradual valuation function as "Cayrol's calculation".

The strength value returned by the valuation function represents the deliberant's ability to support that argument and defend it against potential attacks. The higher the strength level, the easier it is to support and defend the argument, and the harder it is to attack it.

In our SUV example in Figure 1, Cayrol's calculation J (provided in detail in Appendix D) provides $J(\text{"Safe"})=J(\text{"High Taxes"})=J(\text{"High interest"})=0$ and $J(\text{"Taking out a loan"})=-0.33$. The intuition behind this example is that the "Safe", "High Taxes" and "High interest" arguments cannot be attacked or supported, thus have a strength level of 0. The strength value of 0 means that a logical reasoner is capable of defending the argument to the same extent she is capable of attacking it. On the other hand, the "Taking out a loan" argument is considered weaker, as it is attacked by another argument.

In the empirical study [Bonnefon et al. 2008], the authors examined the problem of predicting people’s choice between 2 options (for example, going to movie A or movie B) based on supportive and attacking arguments (pieces of information) relevant to the options at hand. The main and most relevant insight from their work is that a favorable prediction method should not ignore the number of supporting and attacking arguments when predicting people’s choices. In order to integrate this insight into the arguments’ characteristics, we first identify the relation between every pair of arguments using the four General Argumentation Heuristic Rules [Klein et al. 2003], see Definition 3.2. That is, we calculate the relation between every pair of arguments in the argumentation framework using simple heuristics and a simple graph traversal.

Definition 3.2. Let $a, b, c \in A$ be arguments in an argumentation framework $\langle A, R, S \rangle$. a is said to be a *direct* supporter (attacker) of b if aSb (aRb) holds.

The **General Argumentation Heuristic Rules** [Klein et al. 2003] are defined as follows:

- (1) If a supports b and b supports c , then a (indirectly) supports c .
- (2) If a attacks b and b supports c , then a (indirectly) attacks c .
- (3) If a supports b and b attacks c , then a (indirectly) attacks c .
- (4) If a attacks b and b attacks c , then a (indirectly) supports c .

In our SUV example – the “Safe” argument is a *direct* supporter of the “Buy an SUV” argument and “Too expensive” is a *direct* attacker of it. The “Taking out a loan” argument is a direct attacker of the “Too expensive” argument and as such acts as an *indirect* supporter of the “Buy an SUV” argument according to rule 4 of the General Argumentation Heuristic Rules. Following rule 3, “High Taxes” is considered an *indirect* attacker of the “Buy an SUV” argument (as it directly supports the “Too expensive” arguments) and following rule 2, the “High interest” argument is considered an *indirect* attacker of the “SUV” argument (as it directly attacks the “Taking out a loan” argument).

For each argument a , we calculate the number of supporters (direct and indirect), denoted $|Sup(a)|$ and the number of attackers (direct and indirect), denoted $Att(a)$. Then we compute the supporters’ portion $\frac{|Sup(a)|}{|Att(a)| + |Sup(a)|}$ as a member of m_a (the argument’s characteristics). If $|Att(a)| + |Sup(a)| = 0$ then we define the support portion as 0.5. The proposed “Support portion” captures another aspect of the argument’s strength, providing each argument a strength value in the $[0,1]$ interval. In our SUV example – the “Safe”, “High Taxes” and “High interest” arguments have 0.5 support portion values and the “Taking out a loan” argument has a 0 support portion value.

It is important to state in this context that the suggested justification measurements rely solely on the argumentation framework, and as such require only a single, offline calculation of their values for each argumentation framework (regardless of the current deliberation).

Relevance Heuristics: The Relevance values of an argument a capture the proximity of a to the a_l , a_c and Ω arguments. As Relevance values we used the metrics d^1 , d^2 and d^3 defined in Section 3.3, as they provided the highest average prediction accuracy on the gathered data in Experiments 1, 2 and 3. Given the current state of the deliberation, we compute the d^1 , d^2 and d^3 values for every argument a in the argumentation framework as a member of each argument’s characterization m_a . Unlike the Justification values of an argument, the Relevance values may change as more arguments are presented in the discussion.

Confirmation Factor: Confirmation bias is a phenomenon in psychology wherein people have been shown to actively seek out and assign more weight to evidence that

confirms their beliefs, and ignore or underweigh evidence that could disconfirm their beliefs [Nickerson 1998]. In argumentative situations people may present a confirmation bias by selectively considering arguments that reinforce their expectations and disregard arguments that support alternative possibilities or attack their own.

We use the above insights and assign each argument a a value named *confirmation factor* in its characterization m_a . This value depends on the affect that a has on the deliberant’s previously stated arguments. The confirmation factor can be *positive* if a supports (directly or indirectly) previously presented arguments by the deliberant. Or, it can be *negative* if a attacks (directly or indirectly) previously presented arguments by the deliberant. If the relation is ambiguous (both positive and negative) or unknown (the argument does not affect previous arguments presented by the deliberant), then a has a *neutral* confirmation factor.

Given the current state of the deliberation, we compute the confirmation factor for every argument a in the argumentation framework and save it as a member of m_a . This is carried out by iterating over the arguments previously used by the deliberant and using a ’s relation with them as defined by the General Argumentation Heuristic Rules (Definition 3.2) to determine a ’s confirmation factor.

Similar to the Relevance values of an argument, the confirmation factor of an argument may also change as more arguments are presented in the discussion.

In our SUV example – the “Safe” and “Taking out a loan” arguments have a positive confirmation factor as both support S_1 ’s previous argument (the “SUV” argument). Symmetrically, the “High Taxes” and “High interest” arguments have a negative confirmation factor.

3.4.2. Feature vectors.

Hitherto, we described the characterization of each argument a which we denoted as m_a . In order to perform a prediction given a partial discussion, we use the presented arguments in that discussion to compute a feature vector $\vec{x} \in \chi$. These features represent the current state of the deliberation and the deliberant’s preferences in arguments, denoted the *deliberation context features* and the *deliberant features*, respectively. Below we describe how we computed these features.

Deliberation context features: During a deliberation, we account for the last 2 arguments presented by each of the deliberants and indicate which of the deliberants presented the last argument. These 5 features, i.e., the last 2 arguments presented by each deliberant (represented by their labels) and a binary feature representing which deliberant presented the last argument in the discussion, are denoted as the *deliberation context features*. These features are recorded as part of \vec{x} — the features used by the ML model.

Features of the Deliberant: In order to capture the deliberant’s preferences in arguments we aggregated the characteristics of her presented arguments in the discussion. Namely, we analyzed the arguments that the deliberant presented and calculated the average justification value (both the average of J values and the support portion values), the average relevance heuristic values and the percentage of times a confirmatory argument was used (of the number of times at least one was available).

In addition, we hold a *proneness feature* in the $[0,1]$ interval, which indicates the person’s inclination toward accepting a specific position on the discussed issue. For example, in a deliberation on “Capital punishment” a value of 1 means that the deliberant supports the Capital Punishment and 0 means that the deliberant opposes it. The higher the proneness feature value, the stronger the deliberant’s inclination to agree with the discussed issue. This feature stems from the Dissonance Theory [Festinger 1962] which suggests that once committed to an alternative (knowingly or unknowingly), people prefer supportive (consonant) arguments compared to opposing

(dissonant) arguments to avoid or reduce post decision-making conflicts. In order to calculate the proneness feature we distinguished between 2 cases. In cases where the deliberant explicitly expressed her opinion (e.g., “I’m pro Capital Punishment”), the proneness value is simply 1 or 0 (depending on the opinion expressed). In cases where the deliberant’s opinion was not explicitly declared, we assessed the deliberant’s position using her previously stated arguments. We calculated this estimation using the portion of supportive arguments to the discussed issue that the deliberant used during the conversation. Namely, using only arguments supportive of the discussed issue is the same as explicitly stating your opinion.

The above values, denoted as the *deliberant features*, are part of \vec{x} — the input to the ML prediction model.

3.4.3. Analysis of Experiment 1. Each study participant provided 6 argumentative selections, one per each presented scenario. Given a learning period of k scenarios, where $k = 1, 2, \dots, 5$, we took $6 - k$ scenarios from each study participant’s answer set and used the remaining scenarios as training data. For example, for $k = 5$, we removed 1 scenario at a time from all study participants’ selections and used the 5 remaining scenarios for training.

In order to predict the argumentative choice made by study participant i in scenario j given a learning period k , we first calculated the deliberant’s features according to k scenarios (not including scenario j) for all study participants other than i . Then we labeled each calculated deliberant’s features with the actual argument selection made by each study participant in scenario j . The resulting vectors and labels are used to train the prediction model.

We used 3 machine learning algorithms to test the prediction accuracy of our methodology; the Support Vector Machine (SVM), Decision Tree Learning (DTL) and the Multi Layered Neural Network (MLNN). We trained and tested our model on the US-Group and the IL-Group separately (see the groups’ descriptions in Section 3.1.1). For both groups SVM was found to be the most accurate learning model of our observed data as it provided 72% and 78% accuracy in predicting the study participant’s 6th selection when learning from the first 5 selections (US-Group and IL-Group, respectively). DTL and MLNN both yielded less than 68% accuracy for both groups. For the US-Group, as the learning period (k) increased from 1 to 5, SVMs accuracy increased from 42% to 72%. That is, the more observations the prediction model had on the study participants’ selections the higher its prediction accuracy. Random selection naturally provides 25% (in every scenario the study participant was requested to choose 1 of 4 suggested arguments), and predicting the majority’s selection (predicting the most popular selection among the other study participants) provides 41% accuracy. We remind the reader that the Argumentation Theory prediction and the Relevance Heuristics prediction provided less than 41% accuracy on the data collected in Experiment 1. See the learning curve of the SVM model in Figure 2.

Similar results were obtained for the IL-Group, wherein the prediction accuracy ranged from 45% (when $k = 1$) to 78% (when $k = 5$). The accuracy in predicting the IL-Group’s selection was slightly higher than the accuracy in predicting the US-Group’s selections, probably due to the more homogeneous nature of the IL-Group.

In order to check cultural differences we examined the use of the US-Group as a training-set and the IL-Group as the test-set, and vice-versa. In the first setting, wherein the model was trained using the data from the US-Group and evaluated using the data from the IL-Group, the model achieved 76% accuracy. The second setting, wherein the data from the IL-Group was used as training data and the data from the US-Group was used as a test-set demonstrated 69% accuracy.

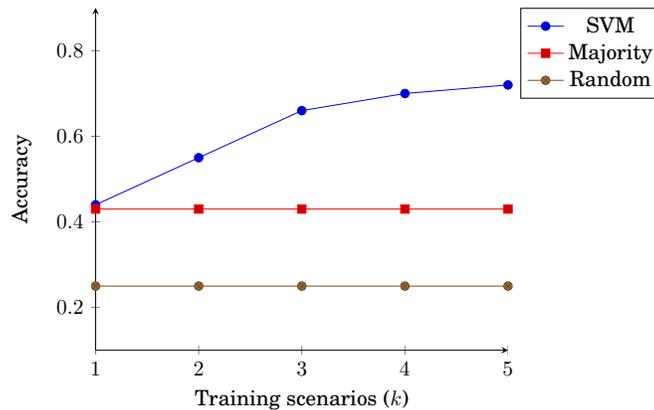


Fig. 2: SVM’s Learning Curve in Experiment 1. The more argumentative choices available for training the SVM, the better its prediction accuracy on unseen scenarios.

The features contributing to the prediction (using an entropy measurement [Gray 2011]) were (in the following order of importance):

- (1) Relevance (edge-distance from a to a_l).
- (2) Cayrol’s justification value.
- (3) Support portion among the influential arguments.
- (4) Proneness.

Most surprising was the fact that the 4 most influential features in the prediction (using an entropy measurement) were the same for both groups, in the exact same order of importance.

3.4.4. Experiments 2 and 3. Each conversation collected on “Capital Punishment”, “Trial by Jury” (Experiment 2) and “Influenza Vaccination” (Experiment 3) was then analyzed argument-by-argument (each argument is considered a step in the deliberation). For each step in the deliberation we computed the deliberation context features and deliberant features and labeled the resulting vector with the argument which was presented next in the discussion.

The evaluation of the model was carried out using the 1-left-out methodology. That is, we learned from $n - 1$ conversations and predicted the arguments presented in the different steps of the left-out conversation.

Recall that the features used by the prediction model rely on the previously presented arguments in the discussion. Therefore, in early stages of the discussion the model may present inadequate predictions. We tested how the prediction quality changes given the steps in which the model is in “learning mode”. That is, we tested how the prediction accuracy changes according to the time period in which the model is required to present predictions.

As a baseline model we used the best model of 8 (simple) statistical models that do not model the deliberant but treat the argument selection process as a stochastic process. The *Bigram model* [Jelinek 1990] of the participant was found to be the best of the 8 models, using perplexity measurements. It outperformed the Trigram model of the participant as well as the Bigram and Trigram statistical models of the other party in the deliberation. It also outperformed the combinations of the above⁸. Bigram mod-

⁸All models used a simple smoothing method to avoid the assignment of 0’s.

eling of the deliberant calculates the probability $P(a_2|a_1)$ for every pair of arguments a_1, a_2 . That is, the probability that a_2 follows a_1 . These probabilities were estimated using a Maximum Likelihood Estimator on the data we collected. Given a_1 as the last presented argument in the discussion, the model predicts $\operatorname{argmax}_{a_2 \in A} P(a_2|a_1)$.

We again trained and tested the SVM, DTL and MLNN models and found that the DTL was the leading method, accuracy-wise. Unlike in Experiment 1, in Experiments 2 and 3 there were many more arguments to consider in the prediction. Naturally, the prediction accuracy declined. However, if we use the probability measurements provided by the learning algorithm we can predict more than 1 argument – that is, we can predict the top k ranked arguments w.r.t. their probability. On the topic of “Capital Punishment”, in Figure 3 we can see how the prediction accuracy increased over the number of predicted arguments (X axis) and the stages from which we began our prediction (the different curves). When predicting the top 3 ranked arguments on the issue of “Capital Punishment” we achieved a prediction accuracy of 71%-76%, depending on the starting phase of the prediction. Very similar results were obtained for the “Trial by Jury” and “Influenza Vaccination” deliberations as well.

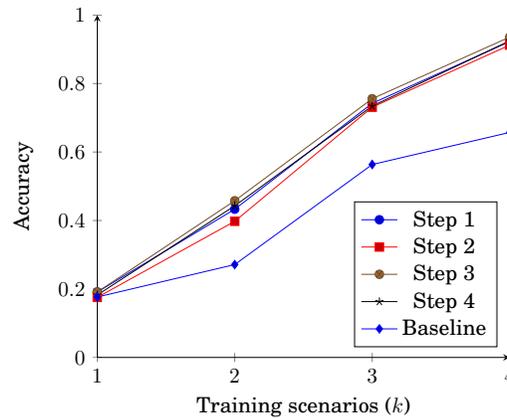


Fig. 3: Prediction Curve for Capital Punishment.

Regardless of the number of predictions, our model’s predictions reached better accuracy than the baseline model. To quantify this difference we used the MRR (Mean Reciprocal Rank) measure [Craswell 2009], which evaluates any process that produces a list of options ordered by their probability of correctness. Our model’s MRR was 0.48 for “Capital Punishment”, 0.58 for “Trial by Jury” and 0.51 for “Influenza Vaccination”, whereas the baseline’s MRR was 0.36 for both “Capital Punishment” and “Trial by Jury” and 0.34 for “Influenza Vaccination” (the higher the better).

When comparing the influential attributes found in Experiment 1 to the ones found in Experiments 2 and 3, we can see that the very same features were found to be influential except for Cayrol’s justification calculation, which was ranked much lower in Experiments 2 and 3. The feature that indicated which deliberant presented the last argument (part of the deliberation context features) took its place. Note that this feature was not applicable in Experiment 1. The prediction accuracy sky-rocketed to 91.2% (“Capital Punishment”), 88.6% (“Trial by Jury”) and 87.7% (“Influenza Vaccination”) in cases in which the deliberant used more than one argument sequentially without interruption. In our study, 100% of the time when a deliberant used more than one argument in a row, the second one was supportive and directly affects the first one.

That is, the indication of which deliberant used the last argument was found to be very influential.

3.5. Analysis using Transfer Learning

In this Section we first describe Experiment 4. Experiment 4 differs from Experiments 1, 2 and 3 as it investigates a *repeated scenario* where we have previous argumentative discussions on the same study participant. Then, we analyze Experiment 4 using the TL approach which is appropriate for handling such settings⁹.

3.5.1. Experiment 4 — Transferring argumentative choices from one domain to another. In this experiment 150 study participants, 110 of whom were Bachelors students studying Computer Science and 40 Intel employees, were recruited. The participants were asked to participate in 3 discussions, each one month apart, on the following topics (in the presented order¹⁰): “Should voting be made obligatory?”, “Should gambling be legalized?” and “Would you get an influenza vaccination this winter?”. In each chat, study participants were coupled randomly such that students were coupled with peer students and Intel employees were coupled with their peers. The coupling was carried out manually by our research assistant who asked the study participants for their preferred time slots and matched every couple accordingly.

During each chat, participants did not know the identity of their deliberation-partner and were instructed to refrain from revealing identifying details such as their name, age, etc. Thus, participants were represented as participant A and participant B during the chat. In order to keep track of the study participants’ argumentative choices across the 3 domains, each participant was assigned an experiment identification number $id \in Identifiers$. When logging in to the chat system, both participants were requested to type in their experiment ids, which were saved for later analysis. Participants were informed of the deliberation topic a week before the chat and were instructed to deliberate over the topic as they would in a face-to-face conversation. Note that for each of the 3 topics, participants were coupled randomly with different deliberation partners.

The chats on “Should voting be made obligatory?” and “Should gambling be legalized?” were annotated by a human expert using the argument corpus provided by Watson, The Debater[©] research team at IBM, and chats on “Would you get an influenza vaccination this winter?” were annotated using the argument corpus constructed in Experiment 3 (Section 3.1.3).

Machine Learning methods, such as the ones suggested in Section 3.4, work only under the assumption that the training and test data are drawn from the same feature space and label space. That is, given a training set of argumentative choices in an argumentative domain α , an ML method generates a prediction model $P_\alpha : \chi_\alpha \rightarrow A_\alpha$, where χ_α is the feature space for the α domain and A_α is the argument set available for the α domain.

Unfortunately, given a training set of argumentative choices from domain α , constructing a prediction model suitable for domain β raises 2 major problems:

⁹Due to the complex logistics of this experiment, in the conversations on “Would you get an influenza vaccination this winter?” one of each paired participants was equipped with an argument provision agent as described in Section 4. Hence, the prediction analysis presented here reflects all study participants in the “Voting” and “Gambling” topics, but only half of the study participants in the “Influenza Vaccinations” topic (i.e, study participants who were not equipped with an advising agent).

¹⁰Due to the high costs and logistics of recruiting study participants for such a long experiment (over 2 months) we used half of the group to test the TLA in Section 4 with the topic of “influenza vaccinations”, therefore the topic had to be the last of the three. Note that the discussions took place a month apart from each other to decrease possible biases.

- (1) **Labels:** The argument set A_α from which the training data's labels are sampled differs from the argument set A_β on which the model is evaluated.
- (2) **Features:** α and β induce different argumentation frameworks, hence $\chi_\alpha \neq \chi_\beta$. Namely, the *context-based features* described in Section 3.4.2 are domain dependent features. The context-based features hold the last arguments presented in a discussion, which differ between argumentative domains.

To bridge over the two issues, we use a feature-based approach for Inductive Transfer Learning [Pan and Yang 2010].

To address the first issue, we used the characterization of each argument (m_a), suggested in Section 3.4, and mapped all arguments, from all topics and conversations, to a joint space called *ArgSpace*.

Definition 3.3. $ArgSpace = J \times D_1 \times D_2 \times D_3 \times C$, where $j \in J$ is the justification value of an argument calculated by Cayrol's calculation, $d_i \in D_i$ is a relevance measurement of an argument and $c \in \{1, 0, -1\}$ is the confirmation value of an argument (as described in Section 3.4.1).

We deployed the function $\varphi : A \rightarrow ArgSpace$ on all arguments from all conversations such that $\varphi(a) = m_a$. *ArgSpace* is the arguments' characterization space, where $m_a \in ArgSpace$ describes argument a in the context in which it is judged (the context in which a reasoner evaluates the argument). That is, in a given state of the discussion, m_a represents the characteristics of a with respect to the current state of the discussion. Notice that *ArgSpace* ignores the topic of the argumentative discussion (Ω) and represents all arguments of all topics and conversations in a single, unified space.

We define *ArgSpace* to be the target space of our TL prediction model. That is, unlike the prediction model described in Section 3.4 which defines A (the argument set of the learned domain) as being the target space of the prediction, the TL prediction model uses *ArgSpace* regardless of the target domain (which in our setting is the "Influenza Vaccinations" domain) to allow it to make predictions across different, and possibly unknown, domains (specifically, across different argument sets). This change has its drawbacks; for example, the proposed prediction model would not predict which argument would be used next in a discussion but rather the *characteristics* of that argument ($m_a = \langle j, d_1, d_2, d_3, c \rangle \in ArgSpace$).

In the SUV example, the four arguments presented to the study participant are mapped to *ArgSpace* in the following fashion;

$$\begin{aligned} \varphi(\text{Taking out a loan}) &= \langle -0.33, 1, 2, 1, 1 \rangle \\ \varphi(\text{High taxes}) &= \langle 0, 1, 2, 1, -1 \rangle \\ \varphi(\text{High interest}) &= \langle 0, 2, 3, 2, -1 \rangle \\ \varphi(\text{Safe}) &= \langle 0, N/A, 1, 1, 1 \rangle \end{aligned}$$

Regarding the second issue mentioned above, we cannot use the feature space χ as described in Section 3.4. χ includes the context-based features as described in Section 3.4.2 which are domain dependent. The context-based features hold the last arguments presented in a discussion, which cannot be used when learning from domain α and predicting on domain β . Therefore, we used a different feature space definition for the TL approach by replacing the last presented arguments in the discussion (i.e, the context-based features) with their characteristics in *ArgSpace*. Note that each argument a , regardless of the topic, can be mapped to a tuple $\langle j, d_1, d_2, d_3, c \rangle \in ArgSpace$ by using a mapping function φ that implements the calculations of j, d_1, d_2, d_3 and c as described in Section 3.4. Namely, we change the context-based features from representing the *labels* of the last presented arguments (e.g, a and b) to the **characteristics** of the last

presented arguments (e.g, $\varphi(a)$ and $\varphi(b)$). Furthermore, in contrast with previous experiments, Experiment 4 provides us with 3 conversations *per study participant*. This provides an additional dimension to consider when transferring argumentative choices from one domain to another. Specifically, when transferring an argumentative choice from domain α to domain β we ought to provide special attention to transferred argumentative choices made by the same study participant on whom we perform the prediction. The rationale is to use all provided argumentative choices from all available domains and study participants in order to generate a prediction. However, when transferring previous argumentative choices made by the same study participant on whom we perform the prediction we will consider these argumentative choices as more influential than choices made by other study participants. In order to distinguish between argumentative choices made by different study participants, we change the feature space to also include the user's identifier (a unique number representing the user in the experiment) as part of the feature vector.

Overall, we change the features used in Section 3.4 by changing the context-based features from the last argument labels to their characterizations and by adding the study participant experiment id. We refer to this new feature space as χ^* .

As a result of the above two solutions, the choice of argument a in a discussion is mapped into a pair $\langle \bar{x}^*, \varphi(a) \rangle$ where $\bar{x}^* \in \chi^*$ and $\varphi(a) = m_a \in ArgSpace$. We emphasize that the above representation of argumentative choices uses a single feature space χ^* and a single label space $ArgSpace$ across all domains, making TL methods applicable.

In order to predict the next argument to be presented in a discussion, we first calculate the feature vector $\bar{x}^* \in \chi^*$ as described above, to represent the deliberant and the deliberation context. Then we predict the characteristics of the next presented argument, that is, we predict $\langle \hat{j}, \hat{d}_1, \hat{d}_2, \hat{d}_3, \hat{c} \rangle = \hat{a} \in ArgSpace$. To that aim, we trained a Multidimensional Regression model¹¹ that receives \bar{x}^* as input and predicts $\hat{a} \in ArgSpace$. The model uses 5 separate SVM regression models [Smola and Schölkopf 2004], each predicting a different value characterizing the next predicted argument in the discussion, i.e., SVM_1 predicts \hat{j} , SVM_2 predicts \hat{d}_1 and so on.

For the evaluation of the Multidimensional Regression model we removed all conversations over each topic, one at a time, and used the remaining conversations (from the two remaining topics) as training data. The conversations from the topic removed are used to evaluate the model. Interestingly, the Multidimensional Regression model achieved a relatively high accuracy with respect to the different examined dimensions of $ArgSpace$; the Mean Absolute Errors (MAE) in predicting j (that is, the mean value of $|\hat{j} - j|$), d_1, d_2, d_3 and c are 0.15, 0.5, 0.4, 0.45 and 0.07, respectively.

Note that the prediction of $\hat{a} \in ArgSpace$ does not naturally translate into an argument in the target domain's argument set. The idea is to search for the argument in the target domain's argument set that its *characteristics* are the most *similar* to the predicted ones, i.e, \hat{a} . For that purpose we need to define a distance measurement between arguments in $ArgSpace$. Given such a distance measurement w we can translate any $\hat{a} \in ArgSpace$ into the target domain's argument set A using $argmin_{a \in A} distance_w|\hat{a} - a|$.

In order to define a distance measurement over $ArgSpace$ we used a Genetic Algorithm (GA)-based method successfully deployed in different applications (a recent example is the painter classification problem [Levy 2014]) which uses the Weighted Nearest Neighbor (WNN) method. In the WNN approach, one seeks to find a weight vector (i.e, chromosome) that will define the distance between every pair of arguments in

¹¹A meta algorithm that allows several one-dimensional regression algorithms to be combined together to allow an M-dimensional input to be mapped to an N-dimensional output.

$ArgSpace$ using a weighted sum; let $a, b \in ArgSpace$ then $distance_w(a, b) = \sum_{i=1}^5 w_i (a_i - b_i)^2$. This distance measurement (in fact, this is a metric) will be used to identify the argument in the target domain's argument set A that is most similar to the predicted \hat{a} using $argmin_{a \in A} \sum_{i=1}^5 w_i (a_i - \hat{a}_i)^2$.

We seek to find a chromosome that will maximize the correct classifications using the above classification approach. To evolve this chromosome we removed all conversations over each topic, one at a time, and used the remaining conversations (from the two remaining topics) as training data. The conversations from the topic removed are used for the fitness calculation of the chromosome, i.e., the number of correctly classified argumentative choices in the conversation from the topic removed.

Given the training data, we randomly generated a population of 500 weight vectors (i.e, chromosomes), with each vector of 5 non-negative numbers representing the weights associated with the different dimensions of $ArgSpace$. We then implemented a stochastic universal sampling module, with double-allele-mixing crossover operators (mating two genotypes by randomizing the parents' alleles) with an 80% occurrence, a Gaussian additive mutation operator with 40% occurrence and 5% elitism for 250 generations. The fitness function for a chromosome is the number of argumentative choices correctly classified in the left-out domain (the higher the better) given the Multidimensional Regression model's prediction \hat{a} . The process was repeated 3 times, arriving at 3 distinct chromosomes – one per topic. In simple terms, we allowed the weight vector population to produce the best weights per target domain, i.e., to evolve the weight vector which produces the highest number of correctly classified argumentative choices in the target domain per the Multidimensional Regression model's prediction.

We then evaluated the 3 calculated chromosomes. For the evaluation we used the left-out topic as the evaluation set. Surprisingly, despite evolving with over-fitting fitness function (the weight vector population evolves with respect to the evaluation set), the accuracy of the best weight vectors was rather poor. When using the Multidimensional Regression model and predicting the 3 closest WNN arguments in the target domain's argument set, the approach averaged 12% accuracy across the 3 domains. These results are worse than relevance-based prediction (see Section 3.3), which does not require *any* training data, and averages 57% accuracy across the 3 domains.

3.6. Discussion on the Prediction of Human Argumentative Behavior

The above results, based on structured argumentation (Experiment 1), free-form human deliberations (Experiment 2) and semi-structured chats (Experiment 3), show that the fundamental principles of Argumentation Theory cannot explain or predict a large part of the human argumentative behavior. Thus, Argumentation Theory, as it stands, should not be assumed to have descriptive qualities when it is implemented with people.

Despite its simple implementation and promising results in predicting human argumentative behavior, the Relevance heuristics have not received any attention in the existing literature on human argumentative behavior.

The results from using ML techniques in predicting human argumentation suggest that the prediction of human argumentative behavior is possible in structured, semi-structured and free-form argumentation *as long as training data on the desired topic is available*. The results also suggest that ML can be useful in investigating argumentation in the real world.

On the other hand, the use of TL did not perform satisfactorily. Apparently, given conversations on the target topic, conversations on different topics (even from the same deliberant) do not enhance the prediction accuracy. Moreover, when no conversations over the desired domain are available, it is better to use the relevance heuristics rather

than deploy a sophisticated TL and GA-based WNN approach. There are several possible explanations for these results, two of which are: (1) People do not use a cross-topic deliberation style – people might deliberate differently over different topics, depending on varying factors such as their knowledge of the topic, their attitude towards the discussed issue, etc. (2) The topics are too different– even if people follow some argumentative patterns, these patterns are hard to detect as they manifest themselves differently in unrelated topics. Some study participants claimed that one or two of the selected topics were not interesting and hence the conversations were rather absent-minded, making it extremely difficult to predict the study participants’ arguments. We hope that these results will inspire researchers in other fields to take on the challenge of investigating cross-topic human argumentative behavior.

Identifying cultural differences has been shown to have a vast impact on automated negotiations [Haim et al. 2012]. In the scope of this work, on two occasions the argumentative cultural difference between Israeli and American study participants was investigated: first, Experiment 1 was performed twice — once with an American group (from AMT) and once with an Israeli group (students). Despite the age and potential cultural differences between the groups the ML model was able to learn from one group and predict for the other without enduring a significant loss in prediction accuracy. Second, and perhaps the most surprising result, is the fact that the results of Experiment 2 and Experiment 3 were shown to be extremely similar both in reference to influential features of the prediction model and in the model’s accuracy itself. There are several major differences between Experiment 2 (annotated phone conversations between American residents¹², in English, recorded in the late 1980’s and early 1990’s) and Experiment 3 (semi-structured chats between Israeli students, in Hebrew, collected at the end of 2014). However, extremely similar results were recorded. The results suggest that using a cross-cultural (US-Israeli) model is possible, though further investigation of this topic is needed.

Additional argumentative, psychological and social issues should be investigated in accordance with the gathered data.

4. AGENTS FOR PROVIDING ARGUMENTS

Given the encouraging results in predicting human argumentative behavior (Section 3), we now direct our attention to the task of utilizing the suggested prediction models in developing argument provision agents.

4.1. Agents’ Policies

There are two main approaches when suggesting an argument to a deliberant: suggest an argument that the deliberant has considered and would (probably) use anyway or suggest innovative arguments – those that the deliberant has (probably) not considered. We designed 9 argument provision policies that implement the two approaches, separately and combined. The agents used our four suggested prediction methods (Section 3) to identify which arguments people are prone to use in a given deliberation state.

— **Predictive agent** (PRD) offers the top 3 ranked arguments using the ML prediction model that were not already mentioned in the discussion. That is, the arguments that best fit the discussion’s situation and the deliberant as learned from the training-set with the exception of arguments that were already presented in the discussion.

¹²Unfortunately, no demographic data is available.

- **Predictive agent with repeated arguments** (REP) offers the top 3 ranked arguments in the prediction model while enabling the provision of arguments that were already used in the conversation, i.e., the agent provides the best fitting arguments to the situation and the deliberant as learned from the training-set without any restrictions on the provided arguments¹³.
- **Relevance-based heuristic agent** (REL) offers the 3 “closest” arguments to the last given argument (using edge-distance). We tested whether the relevance notion could act as a good policy. Note that the REL agent requires no complex modeling or training.
- **Weak Relevance-based heuristic agent** (WRL) offers the 3 least related arguments to the last argument (using edge-distance). The idea behind this policy is to offer the user arguments that she would not naturally contemplate or say.
- **Predictive and Relevance-based Heuristic agent** (PRH) offers the top 2 predicted arguments and the most relevant argument (using edge-metrics) which was not part of the predicted arguments. This agent attempts to enjoy the better of the two policies – PRD and REL.
- **Theory-based agent** (TRY) calculates the extension of the argumentation framework using the Grounded semantics and offers 3 arguments which are part of that extension. Because the extension is usually larger than 3, we offer the 3 “closest” arguments to the last given one (using edge-distance). That is, among the “justified” arguments (according to the Grounded semantics), the agent offers the top 3 relevant arguments at the moment.
- **Transfer Learning agent** (TLA) uses the TL prediction methodology described in Section 3.5. The agent suggests the 3 weighted nearest arguments in the target domain’s argument set to the predicted values in *ArgSpace*. The agent was tested only when no previous data on the target domain was available.
- **Transfer Learning and Relevance agent** (TLR) suggests the 2 weighted arguments in the target domain’s argument set nearest the predicted values in *ArgSpace* and the most relevant argument (using edge-distance) which was not part of the predicted arguments. Similar to the TLA agent, this agent was tested only when no previous data on the target domain was available.
- **Random agent** (RND) offers 3 arguments in a random fashion while avoiding previously used arguments. This policy served as a baseline.

4.2. Experimental Design

In order to evaluate the proposed policies we used the “Influenza Vaccinations” topic that was shown to spark long and quality conversations in Experiment 3.

First, we used Experiment 3’s conversations on “Influenza Vaccinations” to train the prediction model for the PRD and REP agents and Experiment 4’s conversations on “Voting” and “Gambling” to train the TLA and TLR agents¹⁴.

Second, we implemented the 9 different agents; each of them was tested in 17 chats, totaling 153 deliberations with 306 human study participants. Similar to Experiment 3, in each chat we coupled 2 study participants who were asked to deliberate over the same topic of “Influenza Vaccinations”, but in a *free form chat*. Note that only one participant in each chat was assigned a personal agent in order to maintain the

¹³In several conversations in Experiment 2 and 3 we encountered study participants that repeated certain arguments more than once during the conversation, possibly in an attempt to stress the importance of those arguments.

¹⁴As part of Experiment 4, in the conversations about “Influenza Vaccinations”, one of each paired study participants was equipped with an argument provision agent, either the TLA or the TLR agent. Hence, the analysis presented here reflects only *half* of the study participants who participated in Experiment 4.

scientific integrity of the results. From the 306 study participants who took part in this experiment, 286 were Israeli students who were recruited from classrooms, libraries, etc. and 20 were Intel employees. The study participants ranged in age from 18 to 65, with about 60% male and 40% female participants¹⁵.

The identification of the arguments used by the deliberants was done in a *Wizard of Oz* fashion, where during the chat a human expert¹⁶ mapped the given sentences into the known arguments in the previously built argumentation framework (consisting of 40 arguments, see Section 3.1.3). The deliberant who was assigned an agent received 3 suggestions on the right side of the screen in a textual form following each presented argument in the discussion (by either of the deliberants). Suggestions started to appear after encountering 2 arguments in the deliberation to enable a short learning period for the agent. We emphasize that excluding the TLA and TRL agents, other agents had no prior knowledge of the deliberant and required no information from the study participant prior or during the deliberation. Study participants could not select a suggested argument by clicking on it, but had to type their arguments in a designated message-box. This restriction was implemented to avoid “lazy” selections.

All obtained deliberations consisted of 4-20 arguments (mean 9), and took between 5-21 minutes (mean 12). Deliberations ended when one of the deliberants chose to end it, just as in real life. Yet, in order to receive the 15 NIS payment (the price of a cup of coffee and a large pastry in the University cafeteria), the deliberants had to deliberate for a minimum of 5 minutes.

At the end of each session, the study participant who was equipped with an agent was asked to provide her subjective benefit from the agent on the following scale; Very positive, Positive, Neutral (neither positive nor negative), Negative, Very Negative.

4.3. Evaluation

We evaluated the agents’ quality using the study participants’ subjective *Reported Benefit* and the *Normalized Acceptance Rate* which is defined as follows: For each conversation we calculated the percentage of arguments the study participant used from the agent’s suggestion. Then, we averaged those percentages to calculate the *Normalized Acceptance Rate* for each agent. The Normalized Acceptance Rate of the PRH agent was significantly higher than the other agents, averaging 62% acceptance (the study participant’s acceptance rate ranged between 20% and 100%), whereas the PRD agent averaged 26% (0%-50%), the REP agent averaged 19% (0%-50%) and the REL agent averaged 47% (10%-100%). The comparison of the TL agents, TLA and TLR, with the PRH agent is biased. The TL agents do not have training data on the target topic (“Influenza Vaccinations”) and hence cannot compete with the PRH agent which specializes in the target topic. Nevertheless, the TL agents (TLR achieved 42% (0%-80%) and TLA achieved 25% (0%-50%)), were outperformed¹⁷ by the REL agent (47%) which also does not use training data on the target domain. Note that the REL agent does not require any training data, hence it uses a much simpler modeling than the TL agents. The WRL, RND and TRY agents performed very poorly, achieving 3%, 10% and 11%, respectively. The PRH agent outperformed the other 8 agents in a statistically significant manner ($p < 0.05$), using post-hoc univariate ANOVA. See Graph 4.

¹⁵Per Intel’s request, Intel employees were not asked to provide their demographics, hence the presented numbers are based on the student group and our estimation concerning the Intel group.

¹⁶In order to prevent the expert from being biased toward one of the agents, the expert was not involved in any other part of the research and, in particular, in building the agents.

¹⁷This result is not statistically significant.

As for the study participants' subjective *Reported Benefit*, again, the PRH agent outperformed the others in a convincing manner. All 17 study participants equipped with the PRH agent reported a positive benefit (5 reported very positive, 12 reported positive), which is significantly better than the contending agents in the $p < 0.05$ range using Fisher's Exact test. For comparison, the PRD agent achieved 2 very positive benefits, 10 positive and 5 neutral benefits, whereas no one reported very positive benefits, 12 reported positive benefits and 5 reported neutral benefits from the REL agent. Also, only 10 study participants reported positive benefits from the TLA and TLR agents (combined), with the other 24 study participants reporting neutral benefits. RND, WRL and TRY agents again performed very poorly with very few study participants reporting positive benefits.

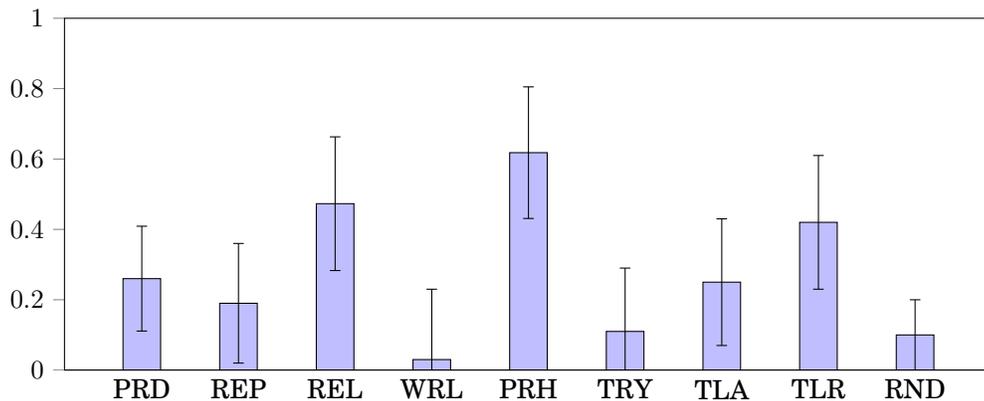


Fig. 4: Normalized Acceptance Rate for the agents. Error bars indicate standard errors.

4.4. Discussion

A strong positive correlation of 0.78 was demonstrated between the study participants' Normalized Acceptance Rate and their subjective Reported Benefit. However, it is hard to claim that the results suggest a causal relation between the two as both are probably correlated with the quality of the suggested arguments, which was not explicitly evaluated.

The PRH agent stood out on both examined axes, the Normalized Acceptance Rate and the subjective Reported Benefit, surpassing the other 8 agents, including the PRD and REL agents which provided the inspiration for its design. A close examination of these agents' results can provide a possible explanation; while the average Reported Benefit from the PRD agent was higher than the one reported from the REL agent, the Normalized Acceptance Rate was lower. We believe that providing predicted arguments is beneficial to the user as it strengthens her beliefs and opinions, yet it does not provide her with any novel insights. Consequently, using the suggested (predicted) arguments might seem trite, and may cause the user to feel unoriginal or like a conventional deliberant. On the other hand, the REL agent provided novel, yet closely related arguments. However, some of these arguments did not fit the beliefs or desires of the user, resulting in a lower subjective benefit. Apparently the combination of the two policies, captured by the PRH agent, takes advantage of the better of the two policies, resulting in a dominating policy.

To our surprise, the lowest ranking agent on both of the axes that we examined was WRL. As the only agent that does not attempt to predict its users' argumentative

behavior we believed that the users would receive novel arguments that would provide an additional point of view which would enrich the deliberants' knowledge and perspective resulting in a good subjective benefit. However, only 1 of the 17 study participants equipped with WRL reported a positive benefit whereas the rest reported neutral benefits.

The TRY and RND agents performed poorly as well. Despite the very limited predictive abilities of Argumentation Theory (Section 3.2), we hoped that we would observe study participants using TRY's suggested justified arguments. Nonetheless, study participants reported low benefits from the agent and showed a low acceptance rate for its arguments.

The TL approach, which failed to predict people's argumentative behavior, has been shown to provide reasonable policies. However, using the TL approach requires prior knowledge about the deliberant (in the form of prior discussions) and rather complex modeling. Hence, the TL agents were dominated by the REL agent which not only achieved better acceptance rates¹⁸ and higher subjective benefits but also required much simpler modeling.

Overall, the results demonstrate that given prior discussions on the desired domain, the PRH is the dominant approach. However, in the absence of such data - for example when discussing a new or relatively unexplored topic - the REL policy can provide an easy to implement methodology which has been shown to outperform theory-based and TL-based policies.

Interestingly enough, none of the study participants reported negative or very negative benefits from any of the agents. The fact that no one reported a negative or a very negative benefit is very encouraging; even when the advice was not used by the study participants, the agent did not "bother" them. This finding indicates that argument provision agents, regardless of their algorithms or policies, hold much potential in real world implementation.

5. CONCLUSIONS AND FUTURE WORK

We performed a pioneer, large scale empirical study with over a 1000 human study participants on the prediction of human argumentative behavior and its implications in the designing and deployment of automated argument provision agents.

Four prediction methods - Argumentation Theory, Heuristics, Machine Learning and Transfer Learning - as well as nine argument provision agents were implemented and extensively tested with hundreds of human study participants.

We first conclude that the prediction of human argumentative behavior is possible and that its use in the designing of argument provision policies is beneficial.

We show that Argumentation Theory, despite its appealing properties, does not provide a useful prediction method nor does it provide a favorable argument provision policy in deliberations. This finding suggests that other aspects of argumentation in addition to justification should be explored to better bridge over the differences between human argumentative behavior and Argumentation Theory.

We further show that the use of the *Relevance* notion, which was first introduced in this study, provides a simple yet beneficial prediction method and argument provision policy. Note that only an argumentation framework is needed for the implementation of this approach. No training phase is needed nor does it require the collection and annotation of argumentative dialogs prior to deployment.

The use of Machine Learning (ML) in argumentation has been shown to provide a valuable prediction method. However, this prediction did not translate into favorable argument provision methods without the inclusion of the relevance heuristics.

¹⁸This result is not statistically significant.

We claim that ML is needed to further investigate argumentative behavior in the real world, and its combination with simple heuristics can enhance its attractiveness as an argument provision policy in deliberations.

The Transfer Learning (TL) approach provided poor results as a prediction method and unfavorable results as an argument provision policy. We believe that a more fruitful use of TL in argumentation can be achieved in simpler and more restricted domains. For example, when predicting the argumentative choices of a salesman's overtime it is reasonable to think that similar persuasive arguments will be used when pitching similar goods - for instance, a Toaster and a Microwave oven. However, this study considered deliberations on varying, unrelated topics which resulted in disadvantageous results of the TL approach.

Regardless of policy, none of the study participants reported a negative or a very negative benefit from the agent's suggestions, with many study participants reporting positive and very positive benefits. This finding emphasizes the potential held by automated agents in the context of argument provision and the promising possibilities that the prediction of human argumentative behavior holds in designing such agents.

During the research process we constructed a rather large annotated corpus, in both English and Hebrew, which we would be pleased to share for future research¹⁹.

We intend to expand the suggested methodology and explore how automated argument provision agents could be used to help people in different argumentative structures such as negotiations and persuasion (see [Rosenfeld and Kraus 2016] for a preliminary report). Note that these argumentative structures are remarkably different from the deliberation structures we considered in this study. For example, in negotiations both parties try to maximize some personal utility in the face of partially conflicting interests, while in deliberations the deliberants merely exchange opinions and beliefs and do not strive to maximize any explicit utility function.

ACKNOWLEDGMENTS

This paper extends our previous reports [Rosenfeld and Kraus 2014; 2015] in several manners. First, by adding an additional 600 study participants this paper enhances the credibility and validity of our previously reported results. Second, it provides a comprehensive analysis of 4 prediction methods and 9 argument provision agents compared to 2 prediction methods and 6 argument provision agents examined before. Finally, this paper covers the investigation of the TL approach which has not yet been investigated in this argumentation context.

Appendices

A. DUNG'S FUNDAMENTAL NOTIONS

Argumentation is the process of supporting claims with grounds and defending them against attacks. Without explicitly specifying the underlying language (natural language, first order logic...), argument structure or attack/support relations, Dung has designed an abstract argumentation framework [Dung 1995]. This framework, combined with proposed semantics (reasoning rules), enables a reasoner to cope and reach conclusions in an environment of arguments that may conflict, support and interact with each other. These arguments may vary in their grounds and validity.

Definition A.1. A Dungian Argumentation Framework (AF) is a pair $\langle A, R \rangle$, where A is a set of arguments and R is an attack relation over $A \times A$.

Conflict-Free: A set of arguments S is conflict-free if there are no arguments a and b in S such that aRb holds.

Acceptable: An argument $a \in A$ is considered acceptable w.r.t. a set of arguments S

¹⁹Some of our data is available at <http://u.cs.biu.ac.il/~rosenfa5/TiiS.experiments.zip>.

iff $\forall b. bRa \rightarrow \exists c \in S. cRb$.

Admissible: A set S is considered admissible iff it is conflict-free, and each argument in S is acceptable with respect to S .

Dung also defined several semantics by which, given an AF , one can derive the sets of arguments that should be considered *Justified* (to some extent). These sets are called *Extensions*. The different extensions capture different notions of justification where some are stricter than others.

Definition A.2. An extension $S \subseteq A$ is a set of arguments that satisfies some rules of reasoning.

Complete Extension: E is a complete extension of A iff it is an admissible set and every acceptable argument with respect to E belongs to E .

Preferred Extension: E is a preferred extension in A iff it is a maximal (with respect to set inclusion) admissible set of arguments.

Stable Extension: E is a stable-extension in A iff it is a conflict-free set that attacks every argument that does not belong in E . Formally, $\forall a \in A \setminus E, \exists b \in E$ such that bRa .

Grounded Extension: E is the (unique) grounded extension of A iff it is the smallest element (with respect to the inclusion) among the complete extensions of A .

The above semantics have been modified to fit the BAF modeling as described in [Amgoud et al. 2008]. This modification is done without losing the semantics' theoretical underpinnings.

B. SCENARIOS USED IN EXPERIMENT 1

The following 6 scenarios were presented to each study participant in a random order. Also, the 4 arguments from which the study participant was asked to select her argument were shuffled as well to avoid biases.

B.1. Scenario 1

This scenario is based on [Cayrol and Lagasquie-Schiex 2005].

During a discussion between reporters R_1 and R_2 about the publication of information I concerning person X , the following arguments are presented:

R_1 : I is important information, thus we must publish it.

R_2 : I concerns the person X , where X is a private person and we cannot publish information about a private person without his consent.

If you were R_1 , what would you say next?

A. X is a minister, so X is a public person, not a private person.

B. X has resigned, so X is no longer a minister.

C. His resignation has been refused by the chief of the government.

D. This piece is exclusive to us; If we publish it we can attain a great deal of appreciation from our readers.

In this example, all mentioned semantics agree on a single (unique) extension which consists of all arguments except "Resigned" (option B) and "Private Person" (R_2 's argument). Thus, all arguments except "Resigned" and "Private person" should be considered *Justified*, regardless of the choice of semantics.

B.2. Scenario 2

This scenario is based on [Cayrol and Lagasquie-Schiex 2005].

A murder has been committed and the suspects are *Liz* and *Peter*. Two investigators (I_1 and I_2) try to decide who the main suspect is: Liz or Peter. The following pieces of information are available to both investigators:

- The CSI-team analysis suggests that the killer is a female.
- The CSI-team analysis suggests that the killer is small.
- Peter is small.
- A witness claims that he saw the killer who was tall.

During the discussion between the investigators the following arguments are presented:

I_1 : "Liz should be our primary suspect, as the murder type suggests that the killer is female".

I_2 : "Also, the witness testimony indicates Liz".

If you were I_1 , what would you say next?

- A. The witness is short-sighted, he is not reliable.
- B. The crime scene analysis suggests that the killer is small, that doesn't fit Liz's physical description.
- C. Liz is tall, that fits.
- D. The killer has long hair and uses lipstick, those are female characteristics.

B.3. Scenario 3

This scenario is based on [Amgoud et al. 2008].

Two doctors (D_1, D_2) discuss whether or not to install a prosthesis on the patient X .

During a discussion between the doctors the following arguments are presented:

D_1 : "The patient cannot walk without a prosthesis, we should install it."

D_2 : "The installation of a prosthesis requires surgery."

If you were I_1 , what would you say next?

- A. We can use local anesthesia to lower the risks in the operation.
- B. The patient is a tour guide, he needs to walk in order to keep his job.
- C. Surgery carries the risk of a post-op infection.
- D. Post-op infections are difficult to cure, we should take this into consideration.

B.4. Scenario 4

This scenario is based on [Walton 2005].

During a discussion between two judges (J_1, J_2) about whether Alice can be accused of breach of contract, the following arguments are presented:

J_1 : "Alice admitted to signing a contract and failed to meet her obligation."

J_2 : "Alice was forced to sign a contract, therefore it is not valid."

If you were J_1 , what would you say next?

- A. A witness said that Alice was coerced by a known criminal into signing the agreement.
- B. The witness in Alice's favor is not objective; she is a close friend of Alice.
- C. The witness in Alice's favor works in the same shop, so she is a valid witness.
- D. A well-known criminal is known for threatening local businesses in Alice's area.

B.5. Scenario 5

This scenario is based on [Parsons et al. 2013].

Two military men (M_1, M_2) discuss whether or not to attack an enemy post. During a discussion between the military men the following arguments are presented:

M_1 : "A high value target is likely to be on the enemy's post, we should consider

attacking it.”

M_2 : ”The presence of enemy troops does indicate it.”

If you were M_1 , what would you say next?

- A. An Informant reported seeing a large number of vehicles in the area.
- B. We should also consider that the mission may not be very safe.
- C. Our UAV reported that there are a small number of fighters in the area.
- D. Our UAV is not reliable; its picture quality is low.

B.6. Scenario 6

This scenario is presented in Example 3.1 and is based on [Arvapally and Liu 2012].

C. ARGUMENT LIST USED IN EXPERIMENT 3

The argument list used in Experiment 3 was presented to the study participants in Hebrew. The following is a translation of that list. Note that the arguments were presented in a random order so as to avoid biases, and study participants were given time to go over the arguments before the chat commenced.

- (1) Vaccination is the best protection against influenza and can help prevent it.
- (2) The flu vaccine increases some people’s risk of getting sick.
- (3) There is a 20
- (4) Immunity develops if the body’s immune system fights a disease on its own.
- (5) For young healthy adults, the shot is less effective as their immune system is strong.
- (6) Not all types of the flu have vaccines, and many of them are more dangerous than those with a vaccine.
- (7) Each year, the flu shot is specially formulated to protect against the standard flu as well as a couple of other strains.
- (8) The CDC recommends that everyone over the age of 6 months get vaccinated against influenza.
- (9) It reduces the risk of getting the flu by 60%.
- (10) Flu shots can be life-saving.
- (11) Some types of flu can cause death in some cases.
- (12) Less than half of the population choose to receive the flu shot each year.
- (13) It’s the responsible thing to do if you care about your grand-parents/parents/children.
- (14) The flu is very rare in our region; the chance of contracting it is low.
- (15) The public is unaware of the severity of the flu.
- (16) Over-use of the flu-vaccine can actually alter flu viruses and cause them to mutate into a more deadly strain.
- (17) Getting the shot will not cause you to get the flu.
- (18) You might experience some flu symptoms in the days immediately following receipt of the vaccine.
- (19) Flu shots may not be safe for some people (due to allergic reactions, for example).
- (20) The shot can cause soreness, redness or swelling in your arm.
- (21) Who can guarantee that a future study will not prove that the shot is harmful in the long run?
- (22) Each person responds differently to the vaccine, depending on his or her age, immune system and underlying medical conditions.
- (23) Most doctors recommend getting the vaccination.
- (24) Some doctors do not recommend getting the vaccination.

- (25) Flu shots are easy to get, they are available in almost every clinic.
- (26) The flu shot is administered for free.
- (27) Getting the shot can take time, you have to wait in line.
- (28) More than 200,000 people in the U.S. are hospitalized every year due to flu-related symptoms.
- (29) Severe cases of the flu usually occur among the old and ill.
- (30) You can spare yourself the aches and pains of the flu and loss of work days.
- (31) You may have the flu virus without showing symptoms and infect others.
- (32) Serious complications are much more likely to occur among the elderly and the ill.
- (33) The flu has potentially serious complications.
- (34) I'm not old and am in good general health.
- (35) I prefer to avoid needles as much as I can.
- (36) I have never had a flu shot and I have never had the flu.
- (37) I'm against vaccinations altogether.
- (38) I may be / I am allergic to the vaccine.
- (39) There is no reason to believe that you are allergic to the shot.
- (40) The vaccination is just another way to get money from people.

D. GRADUAL VALUATION AND CAYROL'S CALCULATION

Definition D.1. Let $W = \langle A, R, S \rangle$ be a BAF. Consider $a \in A$ with $R(a) = \{b_1, \dots, b_n\}$ and $S(a) = \{c_1, \dots, c_m\}$. A **gradual valuation** function on W is $v : A \rightarrow V$ such that $v(a) = g(f_{sup}(v(b_1), \dots, v(b_n)), f_{att}(v(c_1), \dots, v(c_m)))$ where the **summation function** $f_{def} : V^* \rightarrow F_{def}$ (resp. $f_{sup} : V^* \rightarrow F_{sup}$) evaluates the quality of all of the attacking (resp. supporting) arguments together, and $g : F_{att} \times F_{sup} \rightarrow V$ is the **consolidation function** which combines the impact of the attacking arguments with the quality of the supporting arguments.

An instantiation f of f_{sup} or f_{att} must adhere to the following rules:

- $x_i > x'_i \rightarrow f(x_1, \dots, x_i, \dots, x_n) > f(x_1, \dots, x'_i, \dots, x_n)$
- $f(x_1, \dots, x_n) > f(x_1, \dots, x_n, x_{n+1})$
- $f() = \alpha \leq f(x_1, \dots, x_n) \leq \beta^{20}$

Instantiations of $g(x, y)$ must increase in x and decrease in y .

The following instantiation of v is used throughout the paper (taken from [Cayrol and Lagasque-Schiex 2005]). Let $V = [-1, 1]$, $F_{sup} = F_{att} = [0, \infty]$, $f_{sup}(x_1, \dots, x_n) = f_{att}(x_1, \dots, x_n) = \sum_{i=0}^n \frac{x_i+1}{2}$ and $g(x, y) = \frac{1}{1+y} - \frac{1}{1+x}$.

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²⁰ α (β) is the minimal (maximal) value of F_{sup} (resp. F_{att})

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